



# Supplementary Documentation to the financial report for the first quarter of the fiscal year ending March 2023

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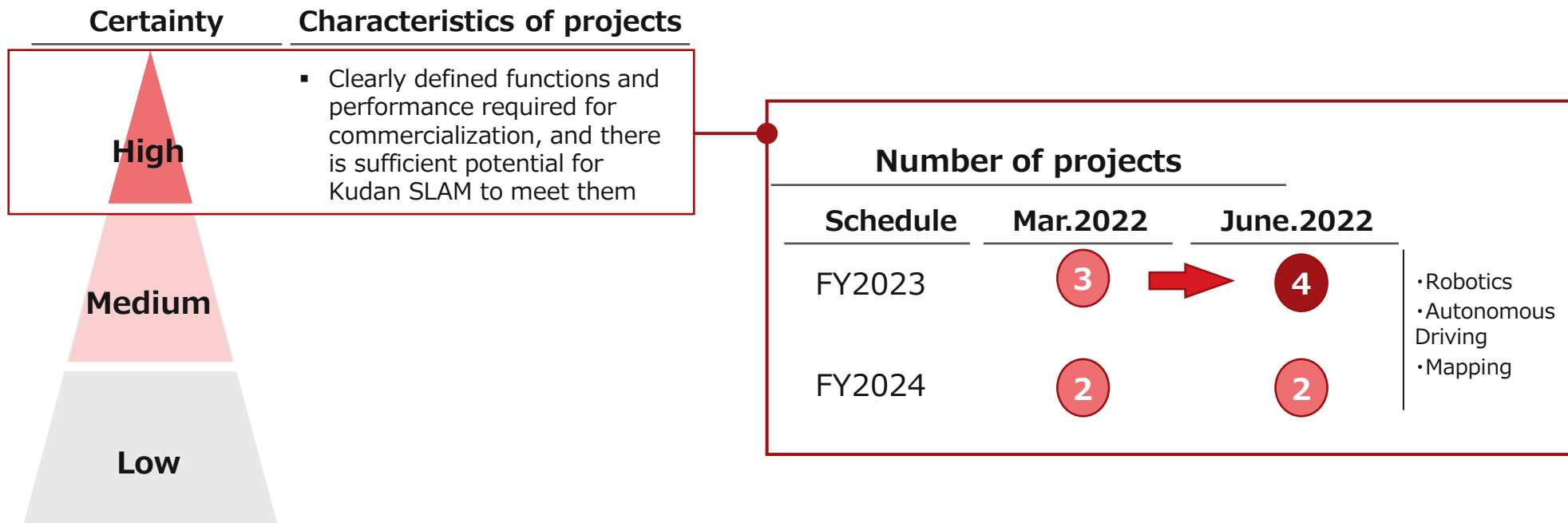
August 15, 2022

Eyes to the all machines







## Beginning of customers' commercialization, and acceleration of the shift from the "preparation phase" to the "harvest phase"

- In July 2022, Whale Dynamic, an autonomous driving technology company in China, has released commercialized products integrated Kudan 3D-Lidar SLAM (KdLidar), along with purchase order of the project in Tier1 city in China
- Due to growing market needs and the maturity of our technology, we expect to increase the number of customers' commercialization projects in the near future and to commercialize 4 projects in FY2023, up from our initial estimate of 3 projects. Strengthening our financial base through financing, we will further accelerate and expand customers' commercialization and develop our solutions business.

## Accumulation of projects toward customers' commercialization



## Examples of projects that have made particular progress

	Company	Algorithm	Progress	Timing
Autonomous driving/ ADAS	 TOP5 automotive OEM	3D-Lidar	Implemented Kudan Lidar SLAM on the cloud to create and provide large scale maps using the cloud. Development for large-scale application is ongoing	Mid-term
	 Major automotive Tier1	Visual	For in-vehicle use. Verification is in progress for commercial implementation in parking assist systems, etc.	
Drone	 Major manufacturer	Visual	Completed availability evaluation using Kudan Visual SLAM and shift to the development and implementation phase for commercialization	Short-term
Robotics	 Major semiconductor	Visual	Testing of Kudan Visual SLAM to be optimized and accelerated for specific processors is in progress	
Mapping	 Construction solution provider	3D-Lidar	Currently testing performance under various environments for finalization	Short-term
	 Mapping solution provider	3D-Lidar	Completed most of the technology integration and concluded a commercial license contract	

# (Reference) About Whale Dynamic

## Company Overview:

Name	Whale Dynamic Co.Ltd.
Representative	CEO and Founder David Yufei Chang
Office	Shenzhen, China
Established	2017
Business	Development and sales of autonomous driving and intelligent transportation products

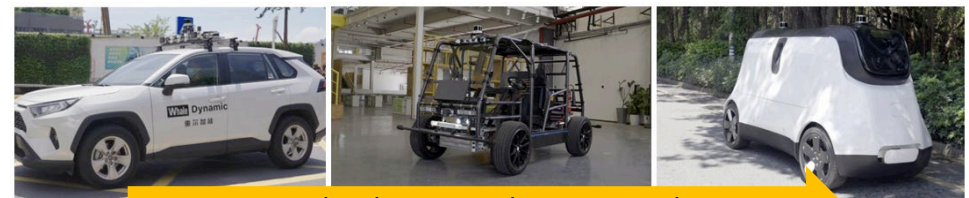
Whale Dynamic is an autonomous driving technology company, founded by David Chang, former senior product manager of Baidu's Apollo autonomous driving platform. The company holds a number of basic technology patents related to driverless vehicle, and its technology is widely used by many transportation providers, tier1 companies, and universities in China.



## Technology and Product Development

Whale Dynamic has traditionally developed core element technologies and full-stack integration in the area of automated driving for passenger vehicles, and has transplanted these technologies into multi-purpose autonomous vehicles designed from zero-base. By employing a good balance of in-house developed and partner technologies for hardware and software, Whale Dynamic could quickly bring high-quality finished, mass-producible, and cost-competitive products to the markets.

Domestic and international industry organizations have recognized the company for its technological capabilities and high level of product perfection. In 2021, Whale Dynamic received several awards, including the Baidu Apollo's Excellent Team Award and Technology Innovation Award at the World Intelligent Vehicle Conference.



Technology Development Path



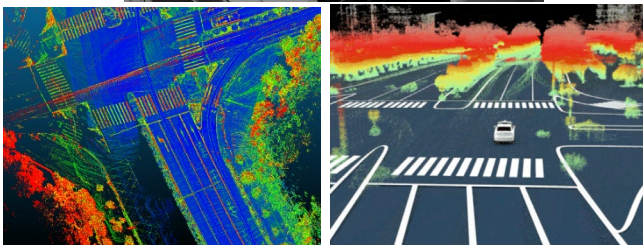
# (Reference) About Whale Dynamic product release



- As the autonomous driving market continuously grows, Kudan and Whale Dynamic have been in technology collaboration since 2021, to respond to the rapidly increasing market needs for driverless delivery and other autonomous mobility-related services.
- In July 2022, the release of commercialized products integrated Kudan 3D-Lidar SLAM (KdLidar) is announced, along with purchase order of the project in Tier1 city in China. KdLidar integration enables highly accurate and robust mapping and positioning in dynamic changing environments.
- Two companies will further strengthen their technology collaboration, and partner in the sales of products to the global market and expand the sales in China.

## High-definition Mapping Kit

- Consists of the mapping hardware kit and software toolchain for HD mapping.
- Hardware can be easily installed in passenger cars as a mobile mapping system, enabling high quality data collection.
- Software toolchain generates high-density point clouds and semantic HD maps with centimeter-level accuracy.



## Multi-Purpose Autonomous Vehicle - WD1

- As driverless delivery vehicle, it can operate autonomously as the electric vehicle on public roads in urban areas and perform various daily tasks.
- Designed and developed from scratch, from hardware (including chassis) to software modules, the sophisticated design, detailed operational scenario design, and extensive on-road testing enables a wide range of use cases.



## Drivable Test Vehicle

- Supports autonomous driving and manual driving in parallel, and is developed with good customization flexibility.
- Fits for validation of autonomous driving technology by developers and researchers of autonomous service enterprises or academic institutions, and makes it possible to quickly conduct practical tests in reasonable cost levels.

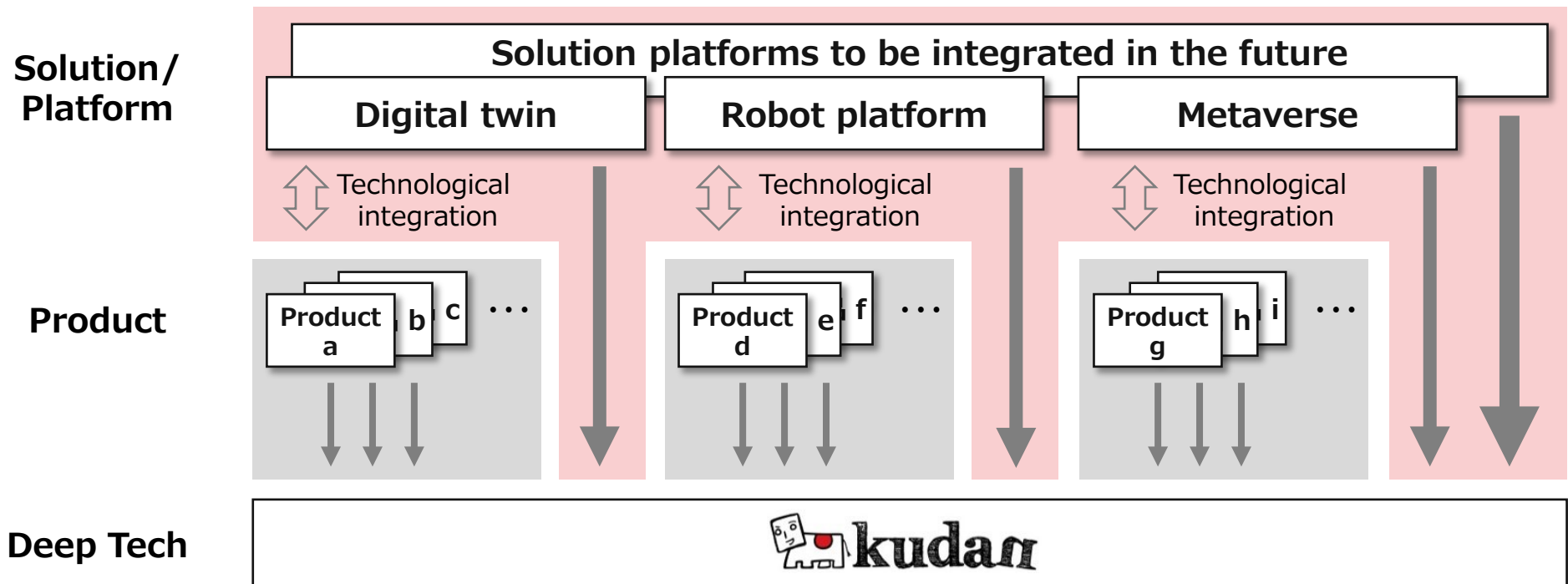




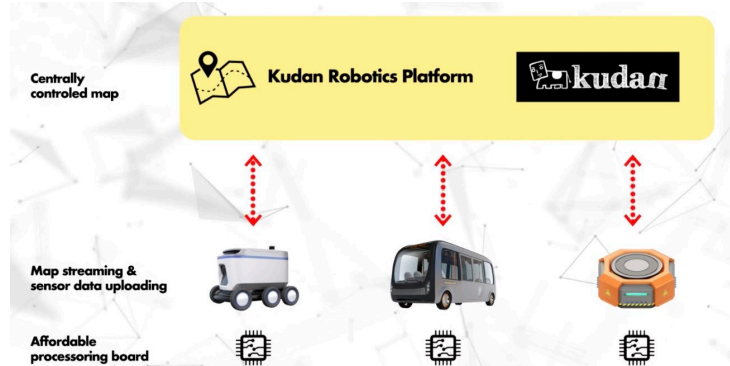
## Solution business launch

- Support the realization of solution platforms that allow multiple products to synchronize or expand their applications centered on Kudan technology
- Aim to improve profitability by taking customers' commercialization as a foothold for the solution business and by generating synergies from the solution business that will support the expansion of customers' commercialization
- See next page for specific solution business concepts

- Newly launched solutions business
- Existing product embedded business
- ➔ Revenue for development support and technology provision



## Solution examples



## ◆ Robotics platform

When a phase of introducing one robot on a trial basis is over and entering a phase of operating multiple types of robots on site, we are beginning to see the issue of disorganized maps and management tools for each type of robot

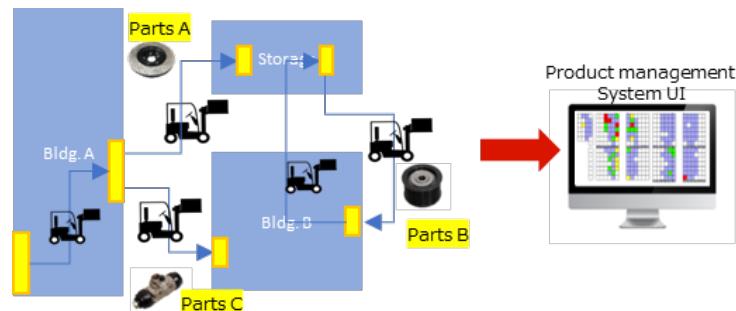
With Kudan's SLAM solution, we can develop **a unified platform that can centrally manage robots** from different companies



## ◆ Mapping solutions

3D maps are used for digital twin and simulation. On-site operations were sometimes difficult since the equipment for acquiring maps has been extremely expensive and it has been necessary to call in specialized companies to acquire and update maps.

Kudan's SLAM solution **enables inexpensive equipment to acquire highly accurate 3D maps**. Also, **the maps include feature points from which location information can be obtained** and can be developed into a number of robotic and Metaverse solutions.



## ◆ Location × AI DX Solutions

By combining location information from our SLAM with AI technology from partner companies, we can provide a completely new DX solution that has never been seen before.

For example, when parts are transported between buildings in a factory using forklifts in any direction, it has been difficult to manage in real time which parts and how many parts are in which storage area. To solve this problem, we will develop a DX solution that can manage parts in real time without using markers, RFID, etc. by **using AI to recognize what parts have been picked up and SLAM to recognize where they have been transported to.**

**SLAM with AI enable**  
real-time, integrated management of complex parts  
inventory status across buildings

## Growing demand for SLAM application to the drone domain

- There is a growing need for industrial drones to improve operational efficiency and reduce labor shortages, and SLAM is expected to be applied in environments where GNSS cannot be used, such as infrastructure inspection, logistics, and mapping and surveying areas in particular
- Kudan Visual SLAM and Kudan 3D-Lidar SLAM are fast and lightweight in their processing, and their high accuracy and robustness make them favorable onboard requirements for autonomous flying drones with limited hardware resources. Currently, we are receiving continuous inquiries from drone manufacturers and service providers in Japan and overseas, and we are working with several of them for commercial implementation.
- In particular, with a major Japanese manufacturer, verification of various performance indicators, including safety, has been completed, and a feasibility study for commercial implementation has been confirmed, so that the development and implementation phase is progressing toward commercialization



Infrastructure inspection



Logistics

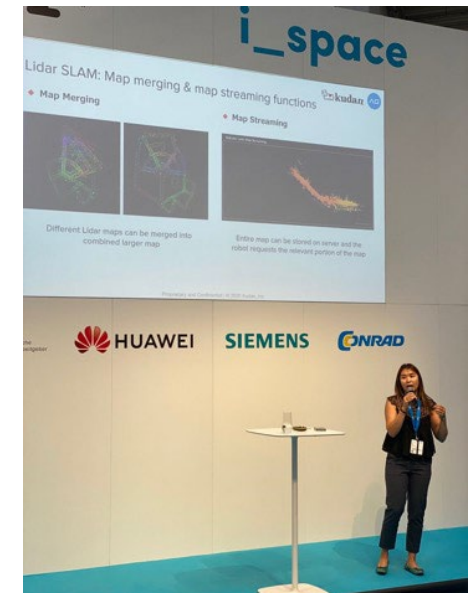
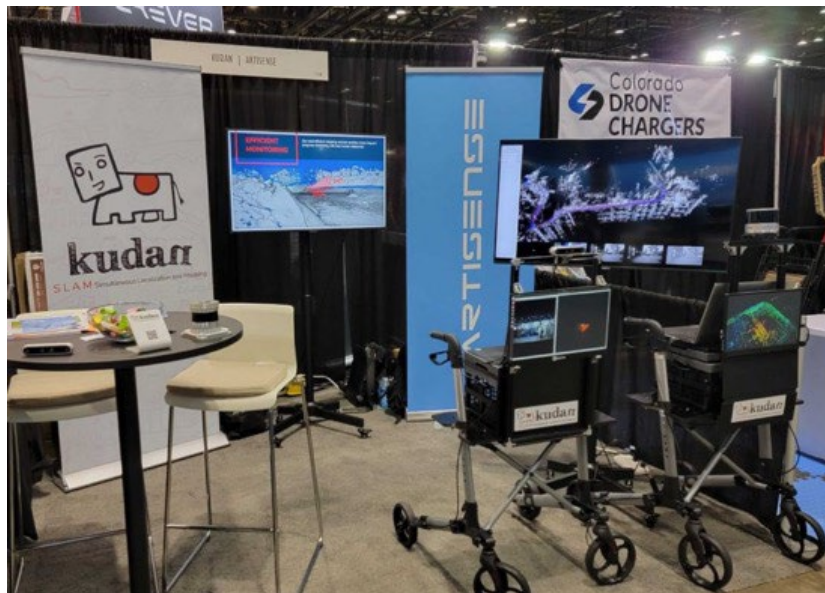


Mapping and surveying





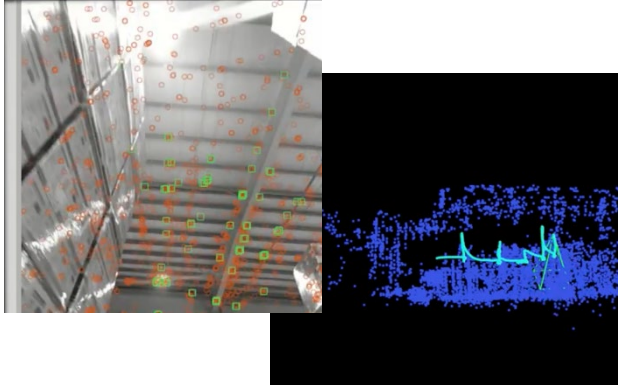



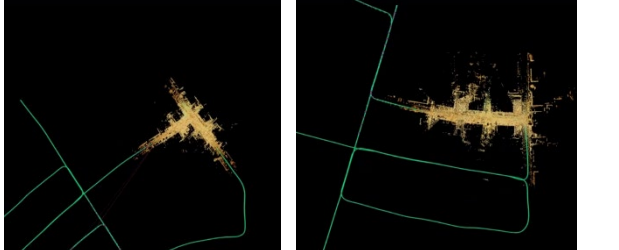


## Expand participation in major overseas exhibitions

- Exhibit at the following exhibitions to introduce Kudan and Artisense's latest SLAM technologies, gather industry's information, and obtain project leads:
  - April 2022: AUVSI XPONENTIAL 2022 (Orlando, Florida, USA)
  - May 2022: AUTOMATICA 2022 (Munich, Bavaria, Germany)
  - June 2022: A3 Automate 2022 (Detroit, Michigan, USA)
- Through participation in these events, we were not only able to actively exchange opinions with industry professionals, but also obtained many business leads, including from major companies. Currently, we are in the process of following up with these companies to develop new projects, some of which have already begun verification using our SLAM



- R&D of Visual SLAM, which integrates Visual SLAM developed by Kudan with Artisense's Visual SLAM, is in progress. This integrated Visual SLAM will be used as our Visual SLAM in the future.

Algorithm	Development item	Examples of ongoing projects
 <p><b>Visual SLAM</b></p>	<ul style="list-style-type: none"> <li>• Integration of Kudan Visual SLAM and Artisense Visual SLAM</li> <li>• Improved processing speed and load reduction for specific processors</li> <li>• Improved stability in environments with changing landscapes and obstacles</li> </ul>	<ul style="list-style-type: none"> <li> Major sensor OEM</li> <li> Major semiconductor Robotic</li> <li> Autonomous Robot OEM Robotics</li> </ul>  <p>Localization of forklift in warehouses with large environmental changes</p>
 <p><b>Lidar SLAM</b></p>	<ul style="list-style-type: none"> <li>• Cloud-based mapping and map streaming for large-scale deployment</li> <li>• Optimized for NVIDIA GPU to improve speed and reduce processing load</li> </ul>	<ul style="list-style-type: none"> <li> Automotive OEM Autonomous driving</li> <li> Mapping solution Mapping in non-GPS environment</li> </ul>  <p>Stream maps from the cloud on multiple devices simultaneously and perform localization on the devices</p>

# Highlights / Financing (1/2)

- Develop business strategy initiatives at the optimum timing in line with business progress centered on customers' commercialization
- Financing for the initiatives is arranged in stages, along with discipline to shareholder value (more on next page)

## Tranche① : 530 million yen

- ▲ Whale Dynamic commercialization

## Tranche② : 530 million yen

- ▲ Second customer commercialization

## Tranche③ : 530 million yen

- ▲ Third customer commercialization

**A**  
Acceleration and expansion of customers' commercialization

- Strengthen customer support and assistance for customers' commercialization
- Strengthen technological development to encourage product penetration for scaling commercialization projects

- Strengthen business development for global expansion of commercialization projects

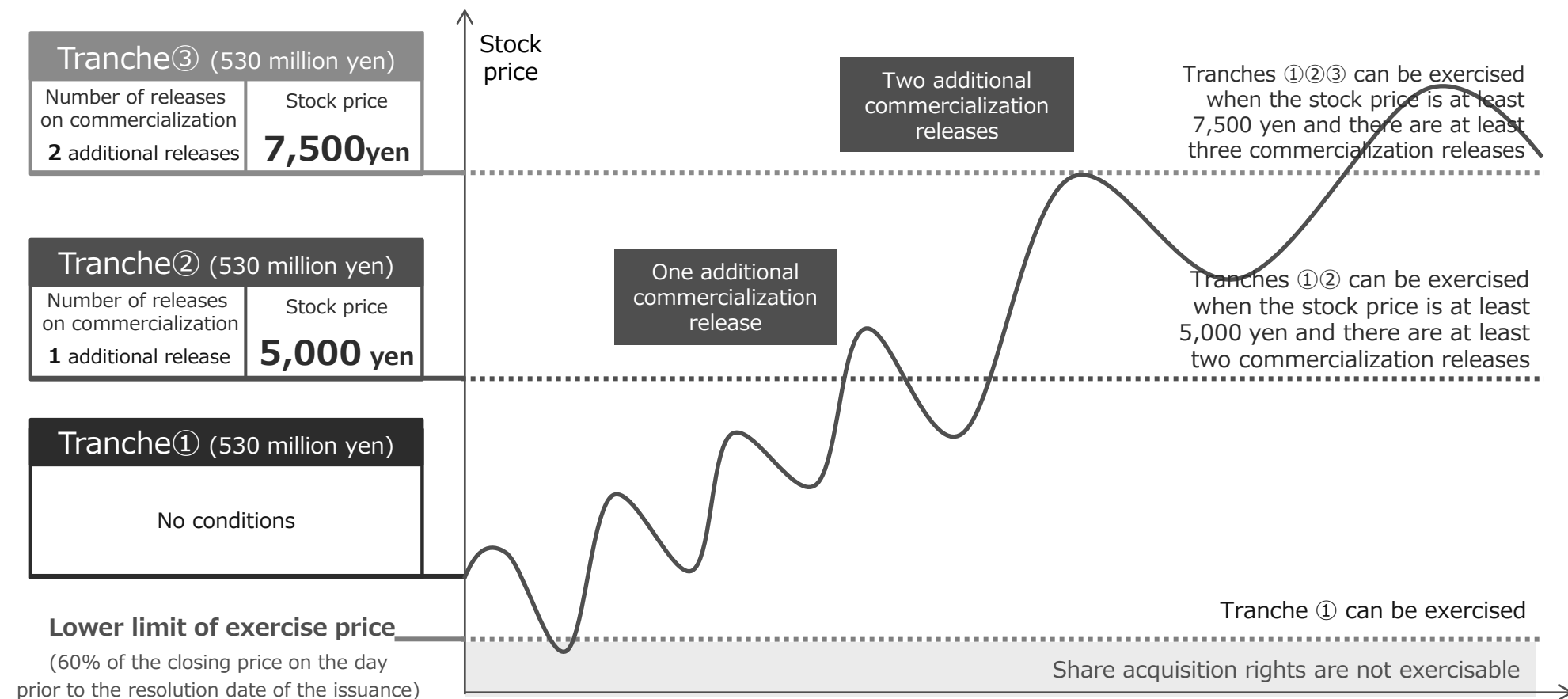
**B**  
Solutions business launch

- Establish a joint development system with partners to demonstrate new solutions

- Strengthen business development and technology development to accelerate demonstration and implementation of solutions

# Highlights / Financing (2/2)

- Raise a **total 1.5 billion yen of growth fund** in stages in line with business growth through share acquisition rights tranche (1) for **the acceleration of Whale Dynamic and further customer commercialization**, and share acquisition rights tranche (2) and (3) with **"commercialization release"** and **"stock price"** as the exercise conditions
- Designed to minimize dilution with a dilution rate of 5.29% through phased financing in line with business growth



## Q. What is the "number of releases on commercialization"?

- A. The number of news releases announced for customer commercialization using our technologies

## Q. Why does Kudan set the commercialization release as the exercise condition?

- A. Our business growth and capital needs for our growth are expected by the realization of customer commercialization

## Q. Are share acquisition rights exercised immediately?

- A. Tranche ① can be exercised immediately, but other tranches are in principle exercisable only when two conditions are met: commercialization release and stock price.

(\*) The above graph of stock price trends is an image only and does not guarantee that the Company's stock price will follow the above trend.



# Performance overview



- Achieved continuous revenue growth by accumulating and scaling projects centered evaluation and development
- With achievement of the customer's commercialization, product license profits will contribute to revenue in addition to license and development support revenue from evaluation and development projects. However, full-scale expansion of product license revenue is not expected until the next fiscal year or later.
- Cost of sales and SG&A expenses increase from the previous year due to the full-year consolidation effect of Artisense, but they are progressing as expected
- Due to the sharp depreciation of the yen, a large amount of foreign exchange gains were recorded in non-operating profit from intra-group receivables and payables. Both ordinary profit and net profit have been recorded in the black.

(Unit: million yen)	Performance for 1Q of FY22	Performance for 1Q of FY23	Forecast for FY2023	Change (from the performance for 1Q of FY22)	Performance For FY22 (Reference)
<b>Net Sales</b>	<b>33</b>	<b>103</b>	<b>500</b>	<b>206.6%</b>	<b>271</b>
<b>Operating Profit</b>	<b>△112</b>	<b>△138</b>	<b>△350</b>	<b>—</b>	<b>△433</b>
<b>Ordinary Profit</b>	<b>△122</b>	<b>40</b>	<b>△300</b>	<b>—</b>	<b>△681</b> (incl. "share of loss of entities accounted for using equity method"(403))
<b>Profit Attributable to Owners of Parent</b>	<b>△122</b>	<b>37</b>	<b>△315</b>	<b>—</b>	<b>△2,237</b> (incl. impairment losses of (1,474))

# Appendix

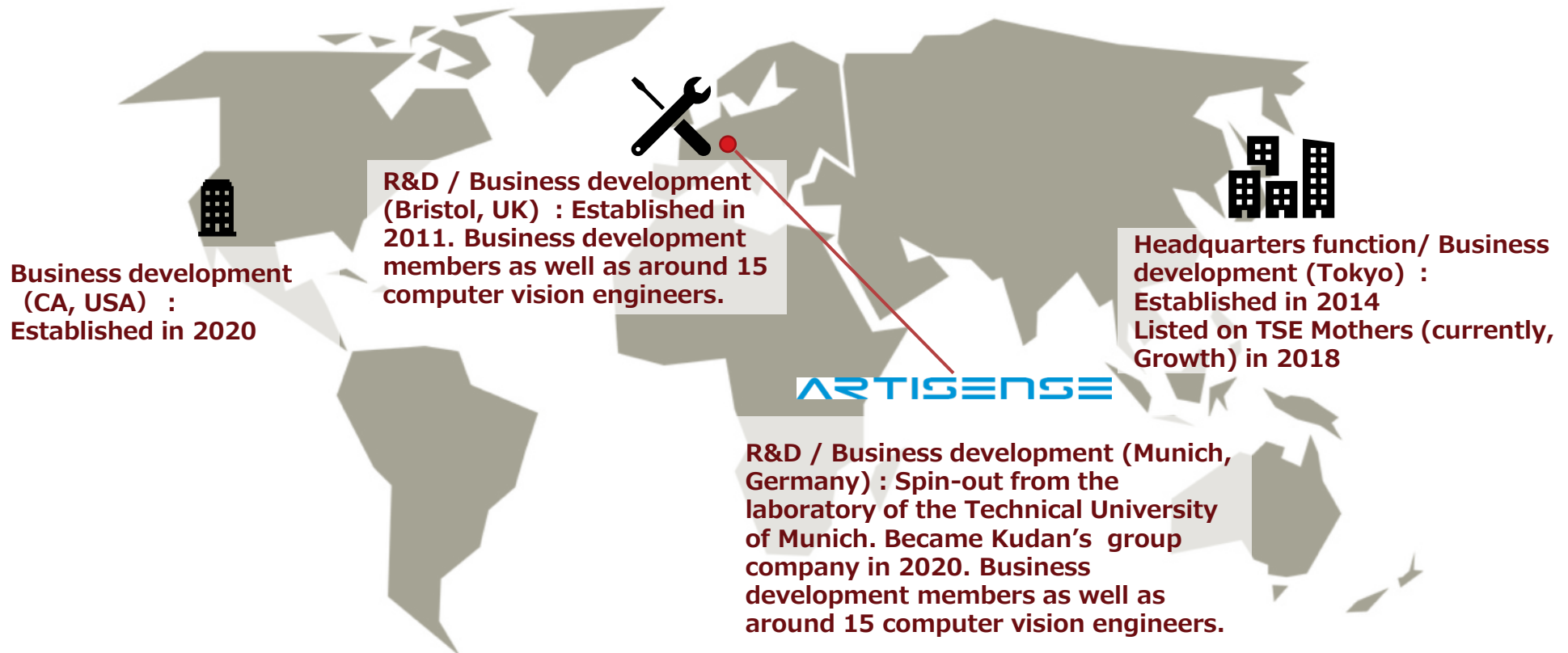
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# **Company Overview**

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# Company overview

- **Kudan is a research and development company that provides AP (Artificial Perception) algorithms and embedded elemental technologies**, specializing in SLAM as the core, which give vision to computers and robots
- Established in the UK in 2011, and with a R&D team of about 30 people in the UK and Germany, Kudan has developed partnerships and customer projects with top global companies. Promoting business for social implementation of AP technology in all next-generation industries including AR, robotics, and autonomous driving

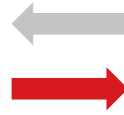




# AP will be the basis for broad range of industries alongside AI

- The artificial perception technology provided by Kudan (providing machines with “eyes”) both complements and operates in unison with artificial intelligence (providing machines with “brains”) to allow a range of machinery (robots and computers) to move and function autonomously

**Artificial Perception**



**Artificial Intelligence**

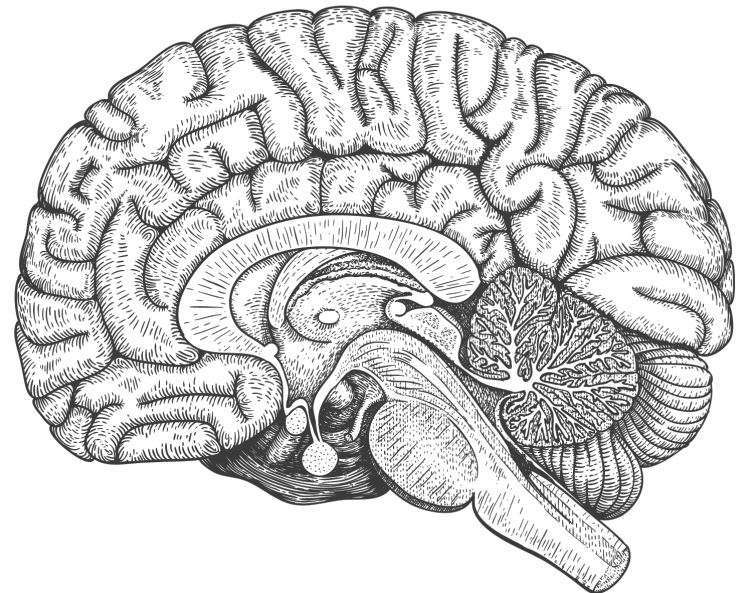
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**The “eyes” of machines, allowing them to perceive and understand their environment**



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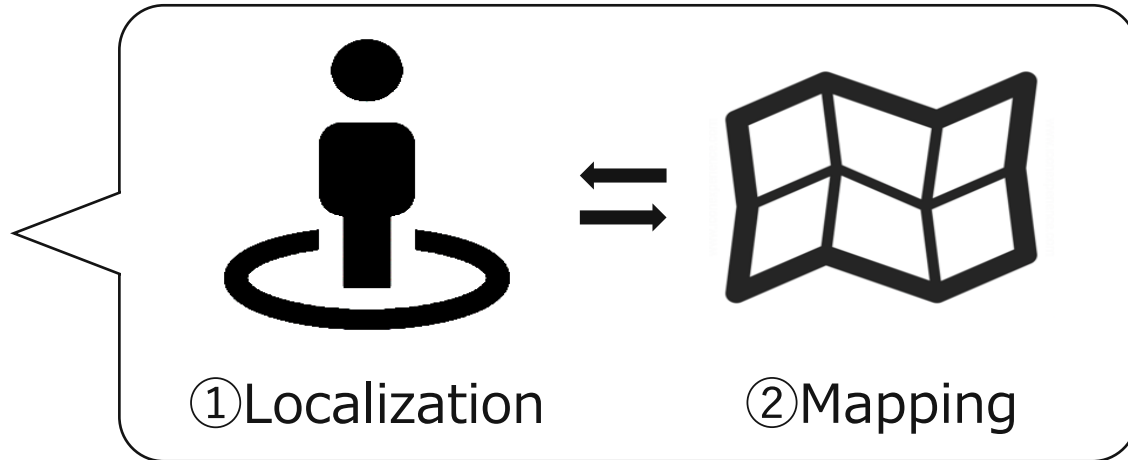
**The “brains” of machines, allowing them to make appropriate decisions**



# SLAM (Simultaneous Localization and Mapping) as the core of AP technology

- AP technology is a group of Deep Tech centered on SLAM (Simultaneous Localization and Mapping)

## SLAM technology (Simultaneous Localization and Mapping)



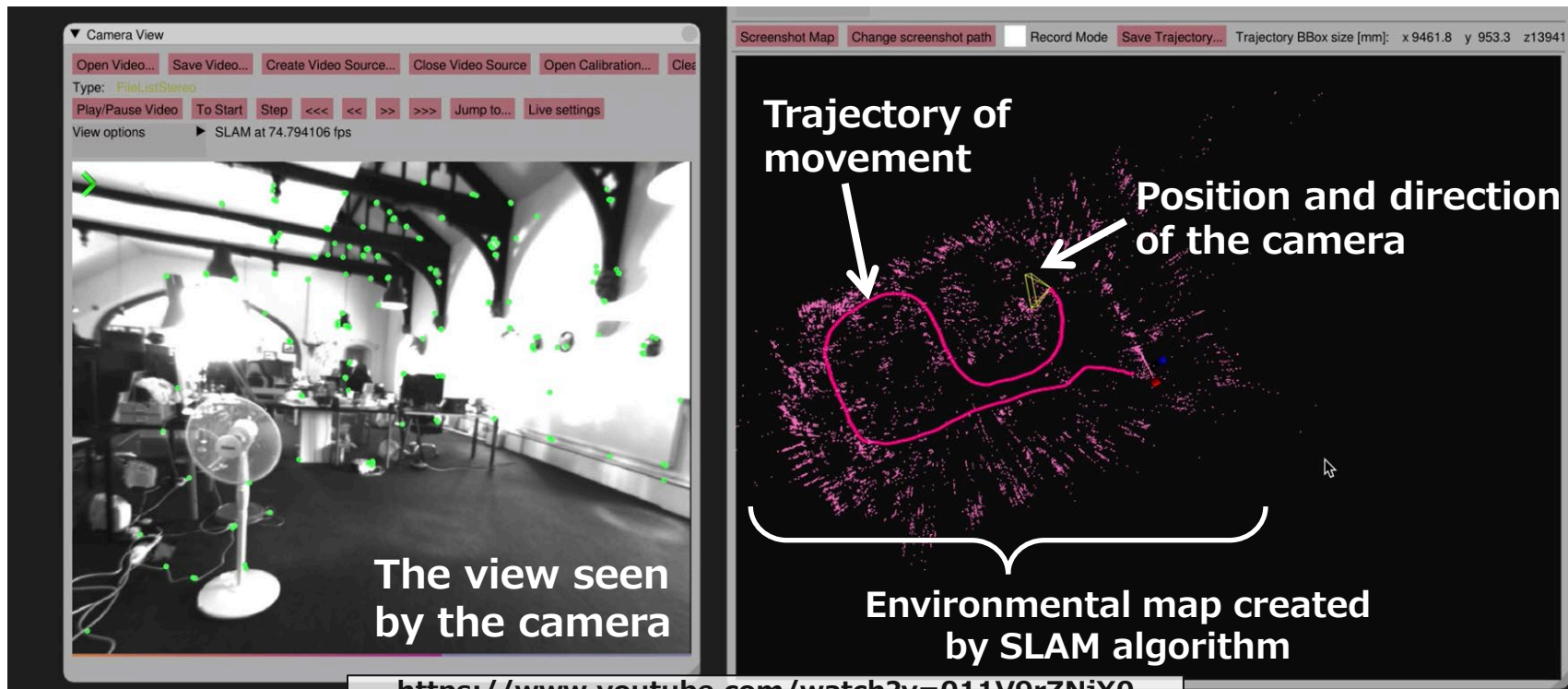
**Re-localization technology**

**Tight-coupling technology**

⋮

# What is SLAM (Simultaneous Localization and Mapping)?

- Technology that simultaneously determines where we are (Localization) and what our surroundings look like (Mapping) based on input from sensors such as cameras and Lidars
- We can keep a track of how we move while creating a map in a new environment (tracking), and recognize where we are based on a map we created beforehand (re-localization)
- Unlike GPS and beacons, which use external radio waves to detect location, SLAM can recognize its own location as a stand-alone software and can be used in a wider range of environments, situations, and use cases



<https://www.youtube.com/watch?v=011V9rZNjX0>

# Kudan is one of the world's largest SLAM development company groups



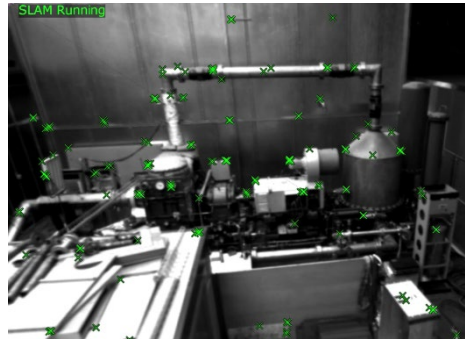
- Company solidification by securing a world-class technical team and the IP (Intellectual Property) of future technology. Achievement of a dominant position in the field
  - Aim for successful breakthroughs via industry-leading technology commercialization
- ⇒ Accelerated integrations of each technology, such as SLAM and Deep Learning, Lidar SLAM and Visual SLAM, Direct SLAM and Indirect SLAM



Strength in turning technology into business, with leading, unique methods of implementing technology, and a global track record.

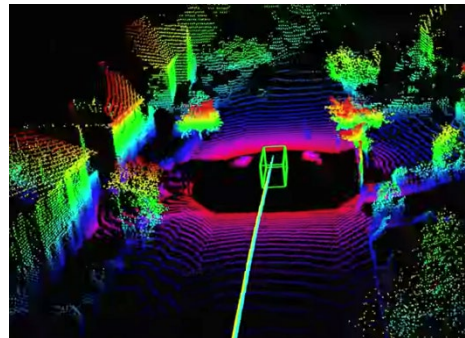
## Indirect SLAM

- Camera image (visual) processing
- Capable of high-speed recognition
- High versatility



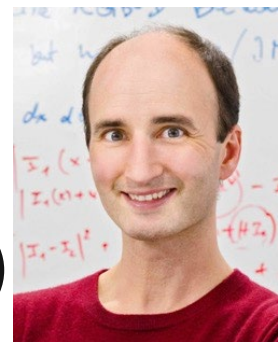
## Lidar SLAM

- Lidar data processing
- Strong in recognizing fast movements
- High stability



## ARTISENSE

Headed by a global leader in self-driving automotive research, Prof. Daniel Cremers, technical experts including Ph.Ds from TUM



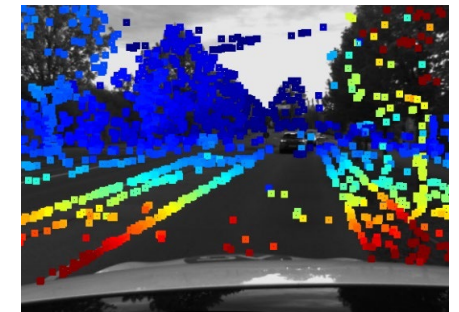
### Prof. Daniel Cremers

Artisense founder and CSO

- Over 52,000 citations of his work in academic papers, h-index 107 (Nobel laureates average 45.1)
- 2016 Leibniz Prize Winner (Germany's most prestigious academic award)
- More than 10 years of joint research with European OEMs, including Daimler, in autonomous driving research

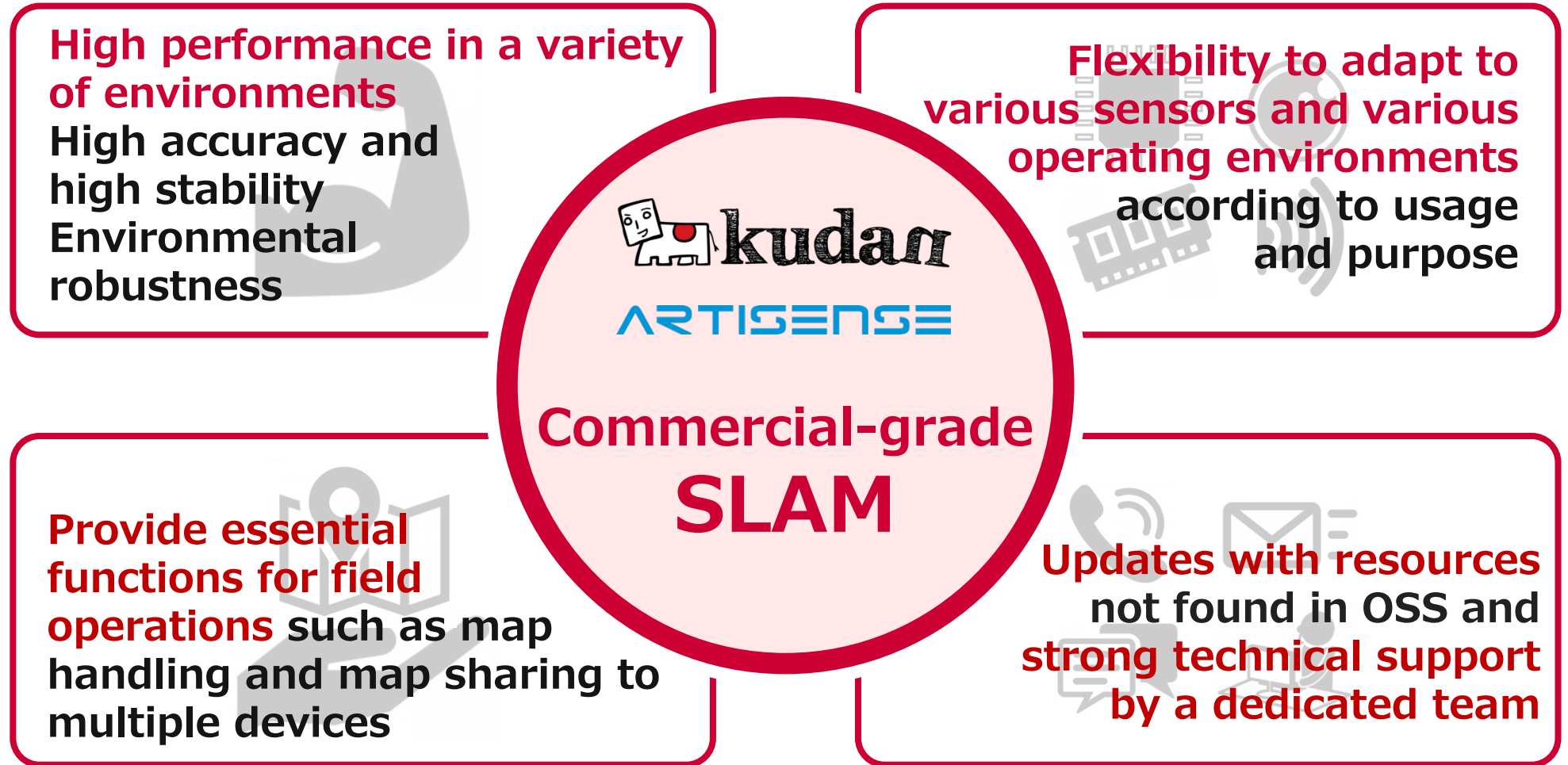
## Direct SLAM

- Camera image (visual) processing
- Capable of detailed recognition
- High stability
- Integration with deep learning models





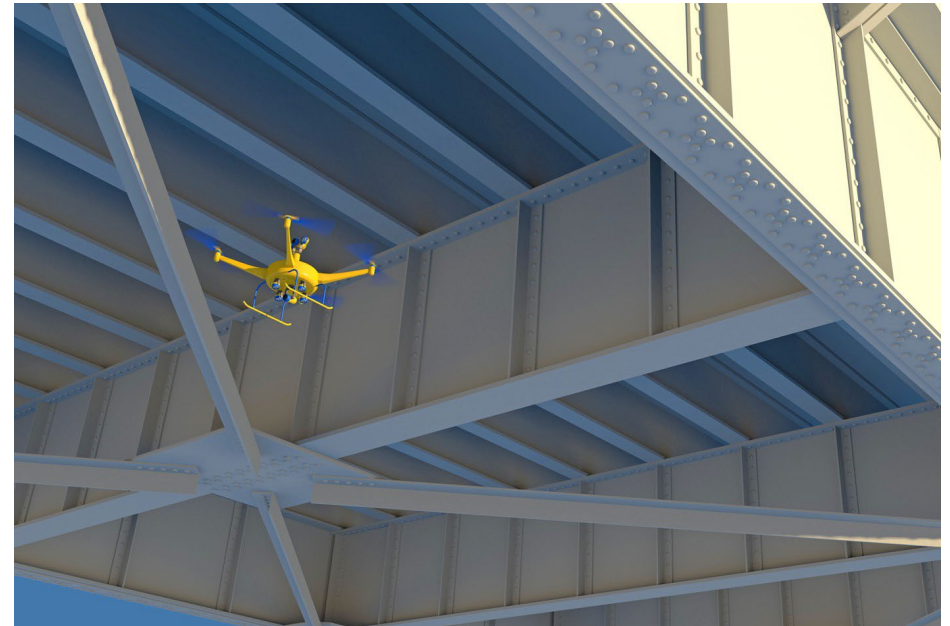
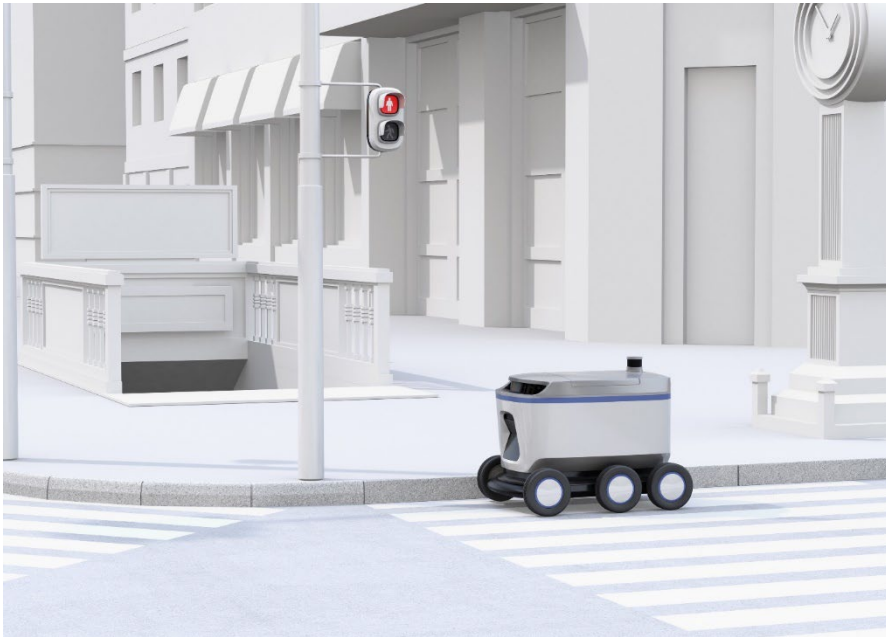
**Unique algorithms refined to overcome the "hurdle to commercialization"**  
many customers who are developing on an OSS (open source) basis are sure to face





# SLAM application (Project Highlights) : Autonomous mobile robots

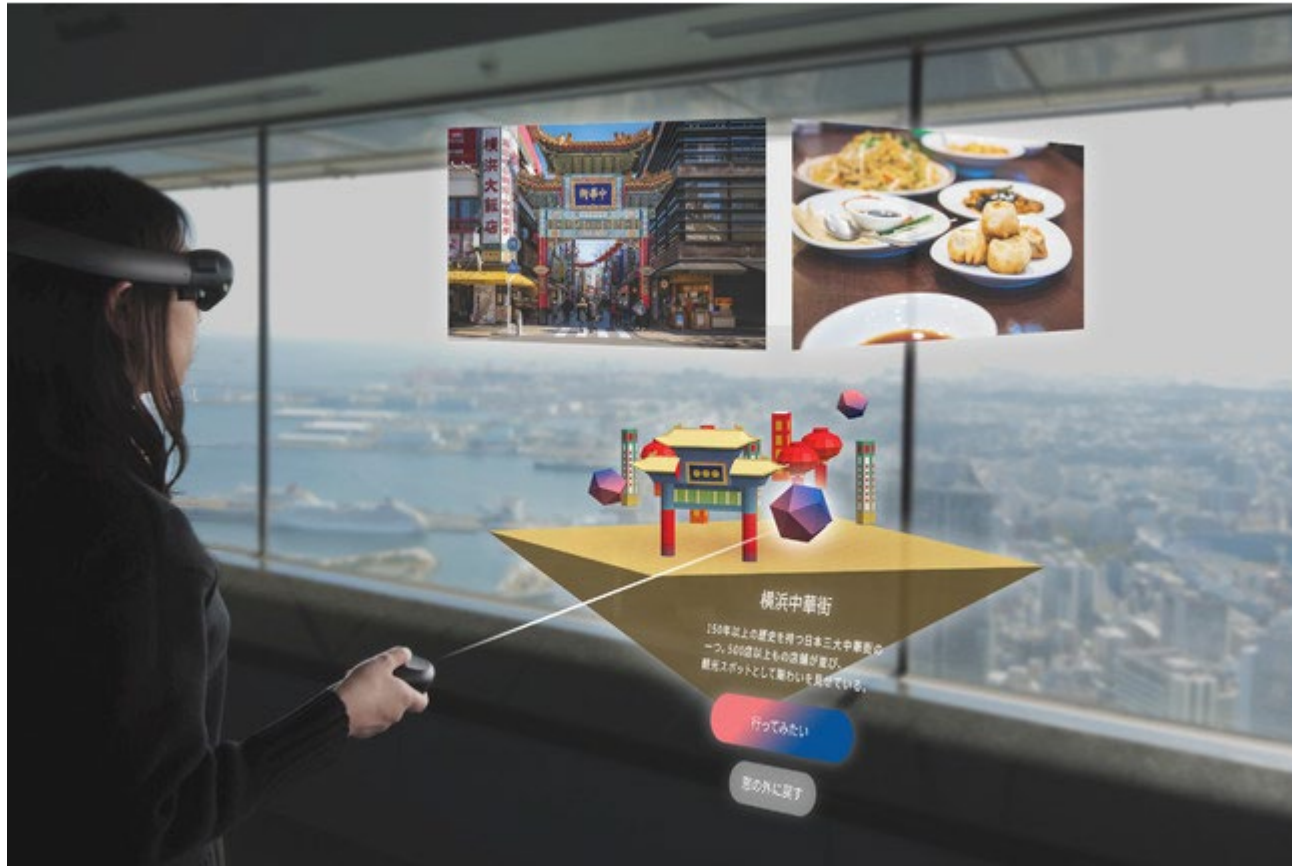
- **Japanese leading telecommunication company** : Progress toward commercialization of a platform that enables the cooperative use of various robots
- **Japanese leading manufacturer** : Development and implementation underway for autonomous flight of drones for infrastructure inspection
- Several other projects including **European robot manufacturer, Japanese leading auto parts supplier, (several) localization of forklift projects**





# SLAM application (Project Highlights) : Implementation in technology infrastructure (AR/General)

- **NTT DOCOMO** : Developing an AR cloud application and released publicly in April 2021
- Several other projects including **leading telecom companies** (three of the top seven global companies), **leading telecom equipment manufacturer** (top global company)

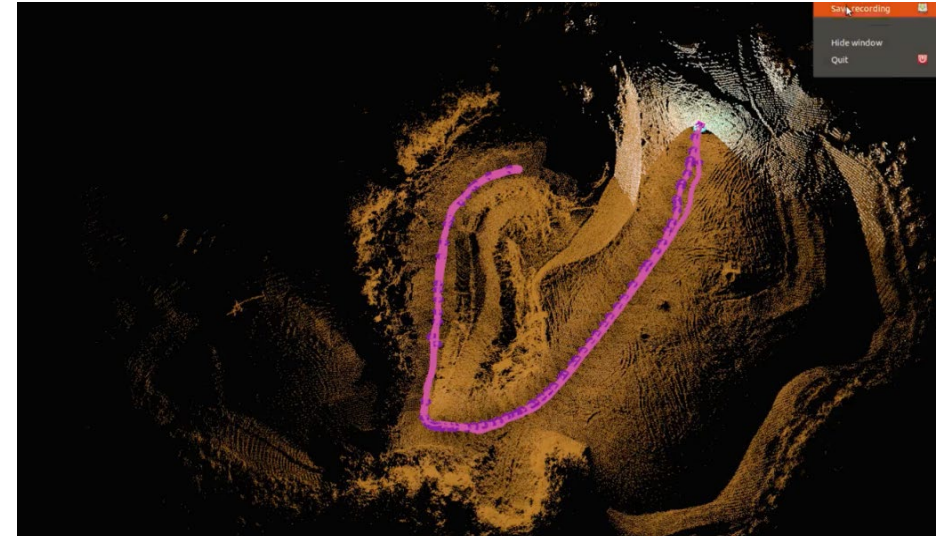
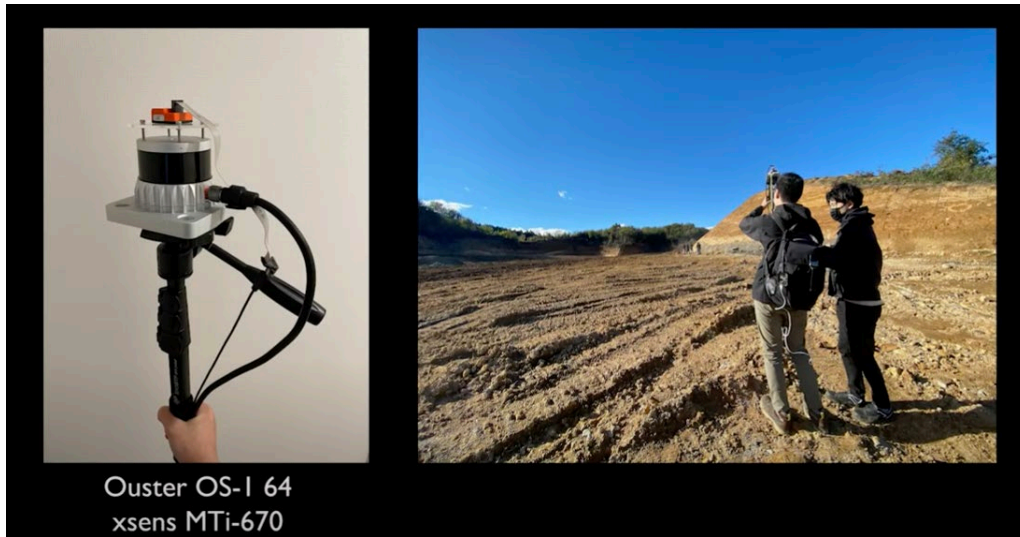


AR cloud with NTT DOCOMO



# SLAM application (Project Highlights) : Next-generation map

- **Atos** : Succeeded in technology validation of handheld mapping, and promote joint development for commercialization
- **US mapping solution provider** : Signed a commercial license agreement and is undergoing final development for commercialization

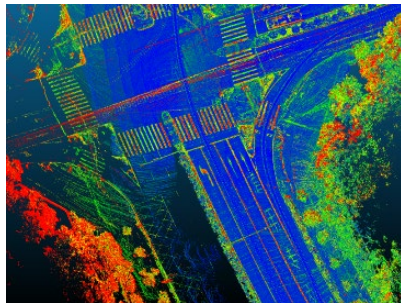


“Construction DX” (= i-Construction\* project) with Atos

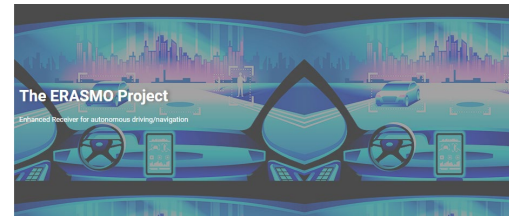
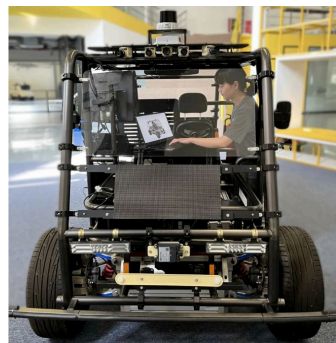
\*i-Construction is an initiative by the Ministry of Land, Infrastructure, Transport and Tourism to improve the productivity of the entire construction production system and make construction sites more appealing.

# SLAM application (Project Highlights) : Automobile-related

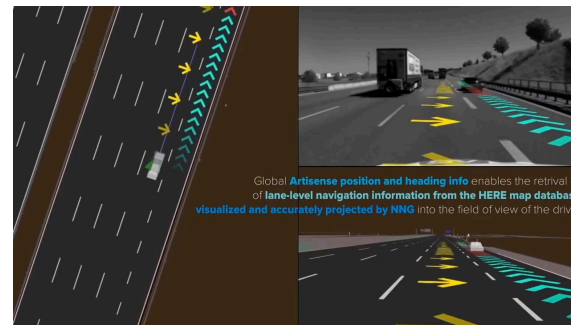
- **Whale Dynamic, an autonomous driving technology company in China** : Products for autonomous driving by integrating Kudan 3D-Lidar SLAM are released
- **“ERASMO”, a multi-year autonomous driving research project funded by an EU research institute** : Participation on this project with other EU companies including Renault and the development of an on-board positioning device enabling fully autonomous driving is in progress (<https://erasmo-gnss.eu/>)
- Not only autonomous driving, but also a wide variety of applications such as driving support and traffic management including **AR navigation development with HERE / NNG**
- Several other projects including **two of the top three global automotive OEMs** and **four major sensor companies**



Whale Dynamic commercialization



ERASMO project



AR navigation with HERE / NNG

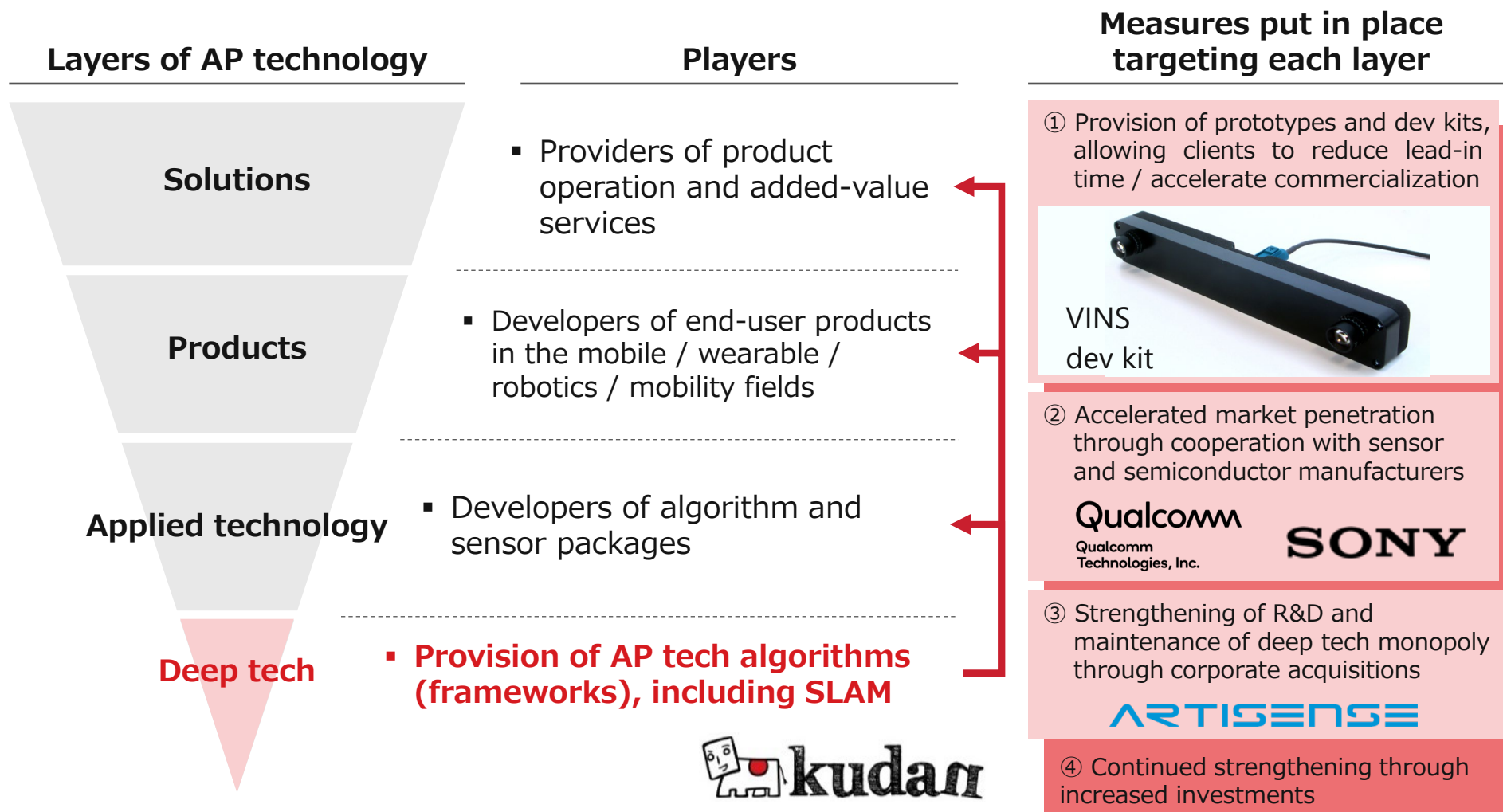
# **Business Strategy**

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# Leader in the Deep Tech layer with strategic positioning

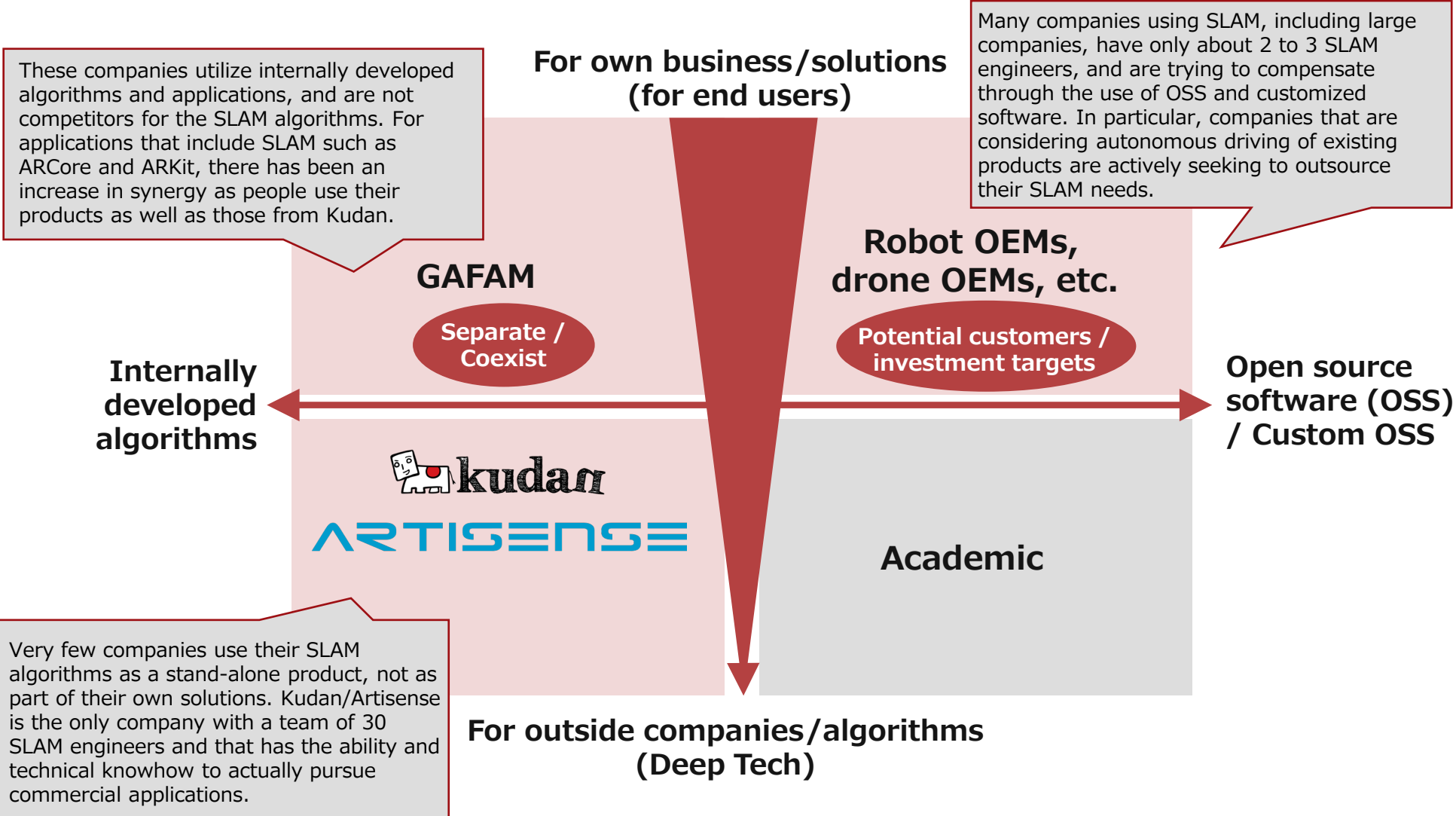


- While maintaining a fundamental focus on the establishment and maintenance of leading position on the low-volatility deep tech layer, measures are being implemented to accelerate the creation and cultivation of markets for Kudan's products in the higher layers of the AP technology pyramid



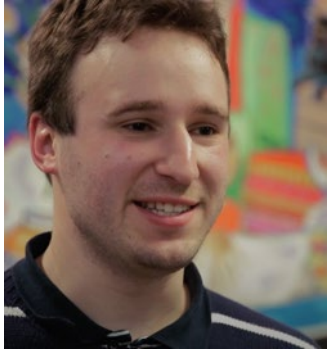
# Expansion of potential customers or investment targets through strategic positioning

Kudan/Artisense enjoys an exclusive position in the area of commercial SLAM algorithms while avoiding direct competition with GAFAM, and many companies that use SLAM technology are also potential customers or investment targets.



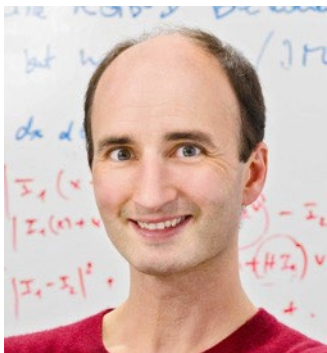


## Research & Development



### **Kudan founder & CTO John Williams**

- Implemented SLAM technology for smartphones ahead of Apple / Google



### **Artisense founder & CSO Professor Daniel Cremers**

- The most influential SLAM/robotics expert in the world  
(The head professor at the Technical University of Munich, about 52,000 citations of his work in academic papers, h-index 107)

## Other management members (previous employments)





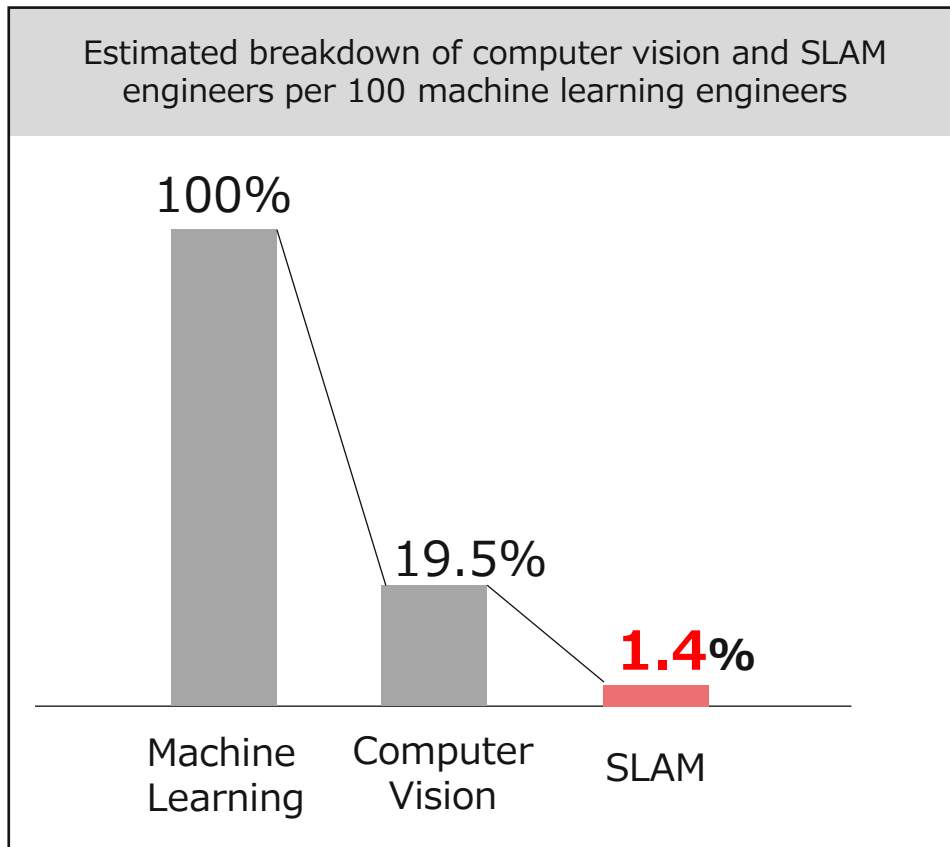
# Acquired world-class technical team to support R&D



Researchers and engineers specializing in SLAM technology are extremely rare, even in the field of computer vision. Despite this, Kudan and Artisense employ many world-class professionals with PhDs in the field. The partnership with industry leaders such as Professor Daniel Cremers and the Technical University of Munich will ensure continued access and expand further to top talent and cutting-edge research.



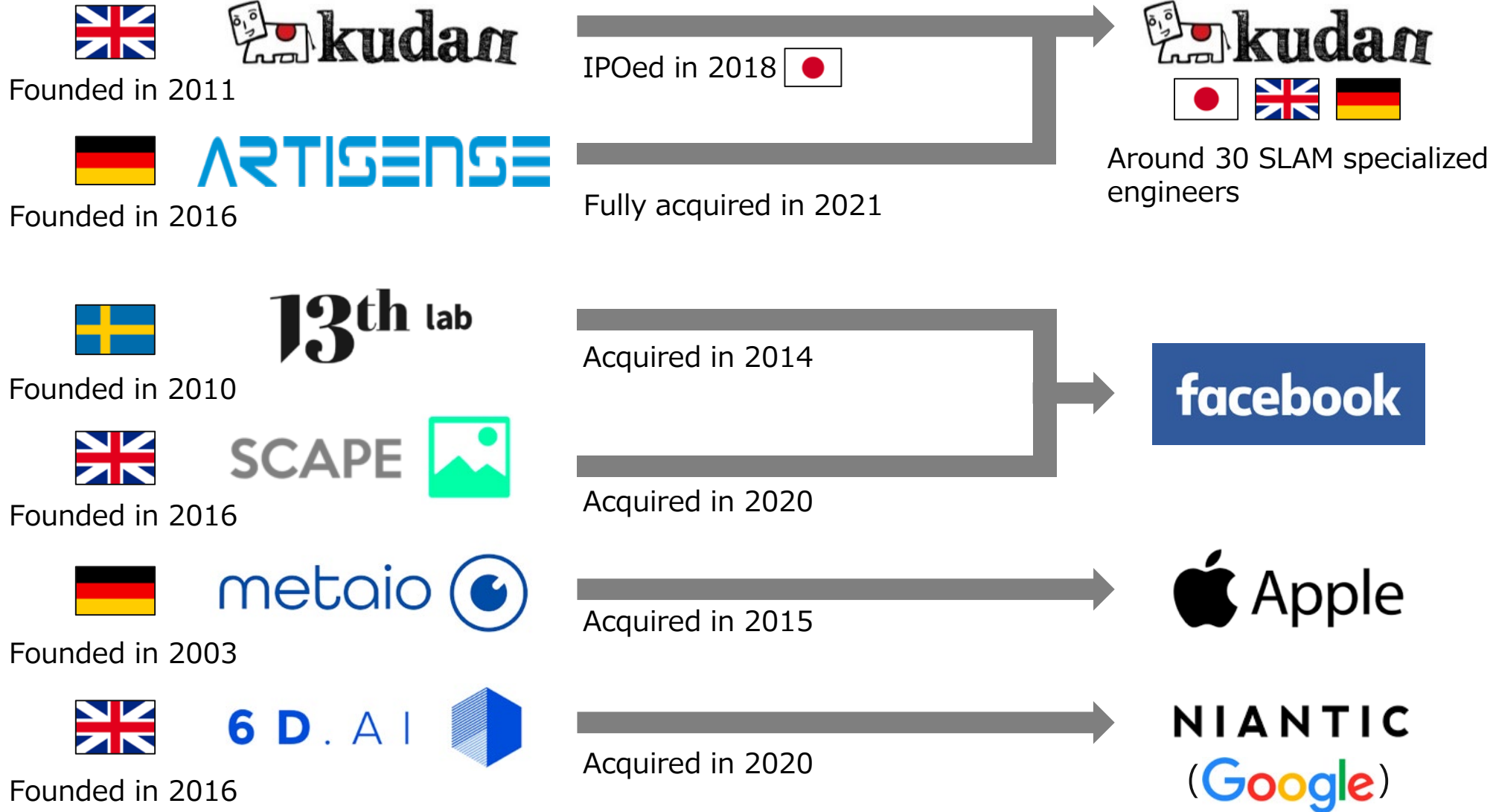
**There is Professor Cremers, a founder & CSO at Artisense**



**Other companies trying to organize SLAM engineer teams of the same level and scale will require large investments in both recruitment and labor costs**

\*Based on a LinkedIn search

# Related technologies are acquired in the world, only a few independent SLAM development companies left



While the increase of acquisitions of the related technologies, Kudan and Artisense leads the market in track record and awareness



- More limited numbers of SLAM-focus / SLAM-feature software companies due to acquisitions by larger technology companies
- Kudan and Artisense have been in a leading position in terms of breadth of offering, track record and awareness in the market

### SLAM-focus / SLAM-feature software player



- Offers Indirect & Direct Visual SLAM and Lidar-SLAM
- Flexible sensor options
- Track records in various applications such as AR, robotics and autonomous driving

### SLAMCORE

- Only Indirect Visual SLAM
- Optimized for limited camera models



- Focus on very specific medical application

### outsight

- Only Lidar-SLAM
- Optimize for their own hardware kit

# Development projects and partnership with global leading players have been increasing



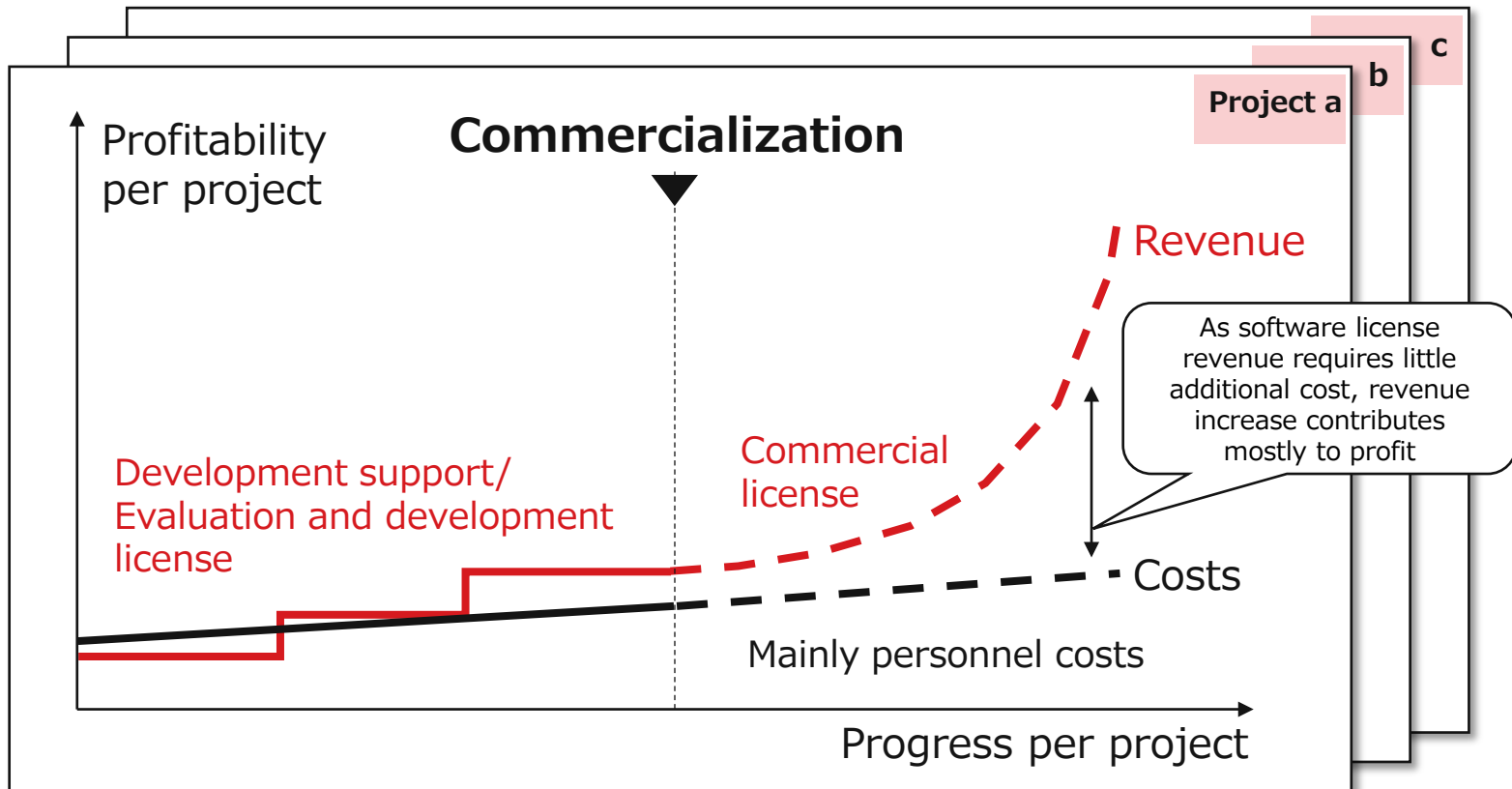
Timing	Main target applications and project overview		
FY20	May.	<b>Robotics</b> ) Partnership with Thales group for next-gen tracking system development	
	Aug.	<b>Robotics</b> ) Alliance with SEAOS for warehouse automation with Autonomous robots with capital tie-up	
		<b>Mobility</b> ) Signed with Japan Unisys to collaborate as Business Scaling Partner	
	Sep.	<b>Mobility</b> ) Partnership with Macnica to develop new value-added solutions for mobility business	
		<b>Robotics, Mapping</b> ) Partnership with Ouster	
	Nov.	<b>AR</b> ) Develop RGB-D SLAM on smartphones with ToF sensor with Sony Semiconductor Solutions	
	Dec.	<b>AR/VR, Mobility</b> ) Partnership with Fixstars to offer accelerated high-performing SLAM	
Jan.	<b>Robotics, Mapping</b> ) Partnership with Cepton on Lidar-SLAM and joint exhibition demo		
	<b>Robotics, Mapping</b> ) Partnership with Velodyne on Lidar-SLAM		
FY21	May	<b>Robotics</b> ) Launch SLAM library for Qualcomm® Robotics RB3 Platform with their technical support	
		<b>Robotics</b> ) Joint development of 3D SLAM demo application with Analog Devices	
	Nov.	<b>Robotics</b> ) Partnership with Vecow to jointly offer integrated solution for autonomous mobile robots	
		<b>AR, Mobility</b> ) Artisense released Automotive AR navigation demo with HERE technologies and NNG	
	Dec.	<b>General</b> ) Achieved 40% image process acceleration with Synopsys ARC EV processor IP on Kudan SLAM	
	Feb.	<b>Mobility</b> ) Provide Lidar SLAM to IIT Bombay autonomous vehicle project team	
Mar.	<b>General</b> ) Joined NVIDIA Inception Partner Network		
FY22	Apr.	<b>AR</b> ) Released utilization of Kudan SLAM in NTT docomo's developing AR cloud	
	May.	<b>Robotics</b> ) Partnership with robotics developer UGO to integrate Kudan SLAM into robotics and joint sales	
	July.	<b>Mapping</b> ) Signed a Developing License General Agreement with BIMEXPERTS and develop joint solutions	
		<b>Robotics</b> ) Partnership with ADLINK, development of AMR, integration of Kudan SLAM into robotics, joint sales	
	Aug.	<b>General</b> ) Joined Texas Instrument's partnership network in robotics	
		<b>General</b> ) Become official SLAM partner with Ouster, a leading Lidar provider, and start offering tools on Website	
	Oct.	<b>Autonomous Driving</b> ) Participation with Renault and other companies in ERASMO, an autonomous driving project by an EU research institute	
Mar.	<b>Robotics</b> ) Exhibited at Intel-sponsored event "Intel IoT Planet ~ Robotics Week"		

# **Growth Potential**

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# Revenue model

- Almost all of customers' projects are in the evaluation or development phase, and we have focused on acquiring and continuing high-quality projects that are expected to achieve customers' commercialization and expand the scale of sales in the future (Business phase in the red due to upfront investment in R&D expenses, mainly engineer personnel expenses)
- Although stable growth can be expected in revenue based on evaluation/development licenses and customer development support in the evaluation or development phase, the most important goal is **to contribute to all next-generation industries and to achieve a significant increase in revenue through commercial license profit with the implementation of Kudan's Artificial Perception technology**

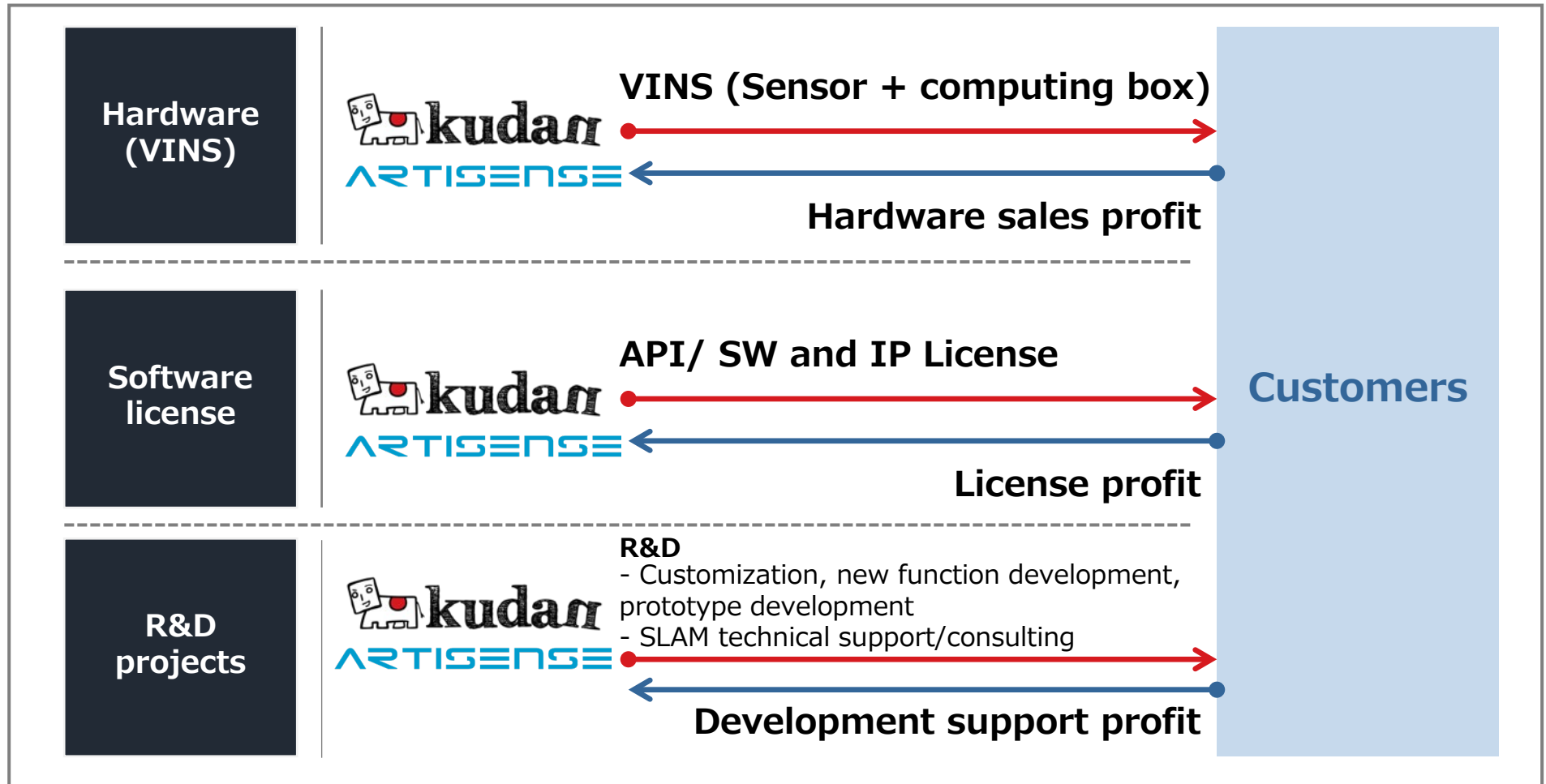




# (Reference) Revenue model (Evaluation/Development phase)

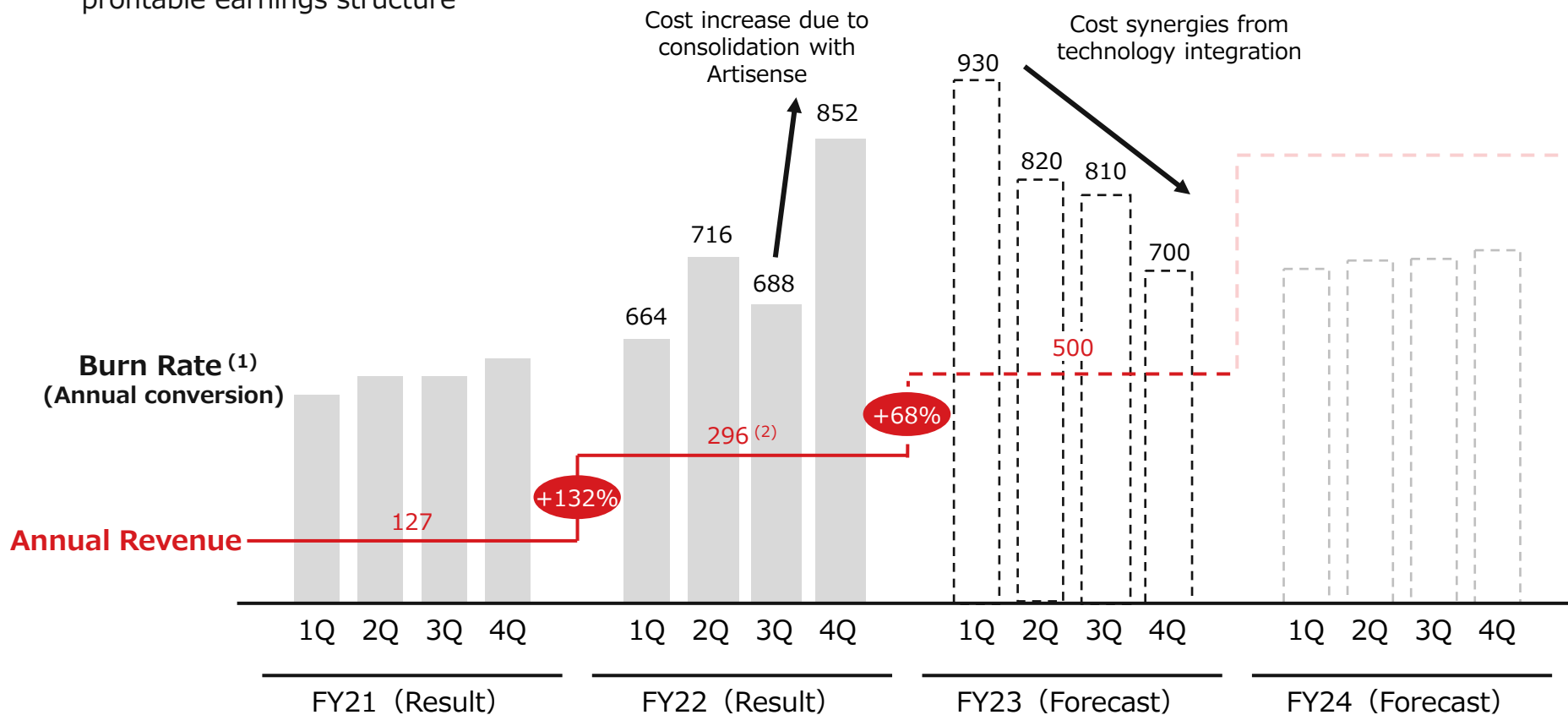


- After commercialization of customer-developed projects, expand license profit through pay-as-you-go billing based on the number of products sold, data volume ,etc. according to the customer's business model (Shift to a stock revenue model)
- In the "evaluation and development" phase, which is prior to the commercialization of customers ' products, we gain revenue mainly from license profit and development support profit based on the development volume and development period.



# About performance forecast for FY2023

- Continued business growth resulting in **+130%** (+170 million yen) year-on-year revenue growth, and projected to grow significantly by **+60%** (+200 million yen) in FY23
- In addition, cost synergies from the technology integration with Artisense (significant efficiency in development through sharing of architecture, modules, etc.) will significantly improve the loss-making structure by FY23/4Q, ensuring profitable earnings structure



(1) Annual costs required for business activities, calculated by each quarterly cost times four. Calculated by deducting R&D subsidy income from total cost of sales, SG&A expenses, non-operating expenses, extraordinary losses, income taxes, etc. (adjusted for seasonal variations, foreign exchange losses and other transitory costs). Prior to FY22/3Q before Artisense was consolidated, Artisense-related costs such as impairment losses and share of loss (income) of entities accounted for using equity method were deducted and only Kudan's costs were totaled. (2) Revenue adjusted for the impact due to accounting standards change

# Performance forecast for FY2023

- Continuous significant revenue growth is expected due to increasing of evaluation and development projects and scaling of projects
- Cost of sales and SG&A expenses are expected to increase from the previous year due to the full-year consolidation effect of Artisense (consolidated only for 3 months in the previous year), but cost structure will be improved by 4Q
- Non-operating profit is expected to include subsidy income from R&D in the U.K. and Germany

(Unit : million yen)

	Performance for FY2020	Performance for FY2021	Performance for FY2022	Forecast for FY2023
<b>Net Sales</b> (Prior to accounting standards change)	<b>456</b>	<b>127</b>	<b>271</b> <b>(296)</b>	<b>500</b>
<b>Operating Profit</b>	<b>9</b>	<b>△451</b>	<b>△433</b>	<b>△350</b>
<b>Ordinary Profit</b>	<b>△12</b>	<b>△1,575</b> (incl. "share of loss of entities accounted for using equity method"(1,232))	<b>△681</b> (incl. "share of loss of entities accounted for using equity method"(403))	<b>△300</b>
<b>Profit Attributable to Owners of Parent</b>	<b>△29</b>	<b>△1,608</b>	<b>△2,237</b> (incl. impairment losses of (1,474))	<b>△315</b>









# Accumulation of projects toward customers' commercialization

- Compared to September in 2021, the overall pipeline has expanded, and in particular, we have succeeded in raising the number of "low/medium" projects to "medium/high" in terms of certainty
- Currently four projects in FY2023 and two projects in FY2024 are highly certain to be commercialized, and projects are actively progressing

Certainty	Characteristics of projects	Number of projects		Commercialization schedule
		Sep. 2021	Mar. 2022 <sup>*</sup>	
High	<ul style="list-style-type: none"> <li>Clearly defined functions and performance required for commercialization, and there is sufficient potential for Kudan SLAM to meet them</li> </ul>	4	6	<ul style="list-style-type: none"> <li>4 FY2023</li> <li>2 FY2024</li> </ul>
Medium	<ul style="list-style-type: none"> <li>Evaluation and development projects that have already passed performance verification</li> <li>Limited risk to commercialization (competition, performance, price, etc.)</li> <li>Specific timeline for commercialization is clear</li> </ul>	17	22	
Low	<ul style="list-style-type: none"> <li>Evaluation and development projects that have already passed performance verification</li> <li>Specific timeline for commercialization is unclear</li> </ul>	23	26	

\*The number of "Certainty: High" is updated from 5 to 6 as of June 2022. Changes from September 2022 were AR/VR: -1 (due to delay in development progress), robotics/autonomous driving: +3.

# Highlights of projects accumulated for customers' commercialization

Market	New・Ongoing (Comparison as of September 2021)	Company	Algorithm	Overview
Robotics	Ongoing	 Major telecommunication	Visual SLAM	A platform that enables the cooperative use of various robots
	New	 Major semiconductor	Visual SLAM	Visual SLAM optimization and SLAM packaging for specific processors
Autonomous driving・ADAS	Ongoing	 TOP5 automotive OEM	Lidar SLAM	Autonomous driving project for general passenger cars
	Ongoing	 Major automotive Tier1	Visual SLAM	Development of driver assistance functions with cameras installed in commercial vehicles
Metaverse (AR/VR)	Ongoing	 Major camera OEM	Visual SLAM	Development of Mixed Reality headset for medical applications
	Ongoing	 UK engineering company	Visual SLAM	Development of digital twin solutions for industrial facilities
Mapping	Ongoing	 Mapping provider	Lidar SLAM	Mapping solutions in non-GPS environments
	New	 Construction Solution Provider	Lidar SLAM	Development of simple mapping device for construction and civil engineering

\*This page shows highlights of the projects which are close to commercialization, have made a significant progress toward commercialization, etc.



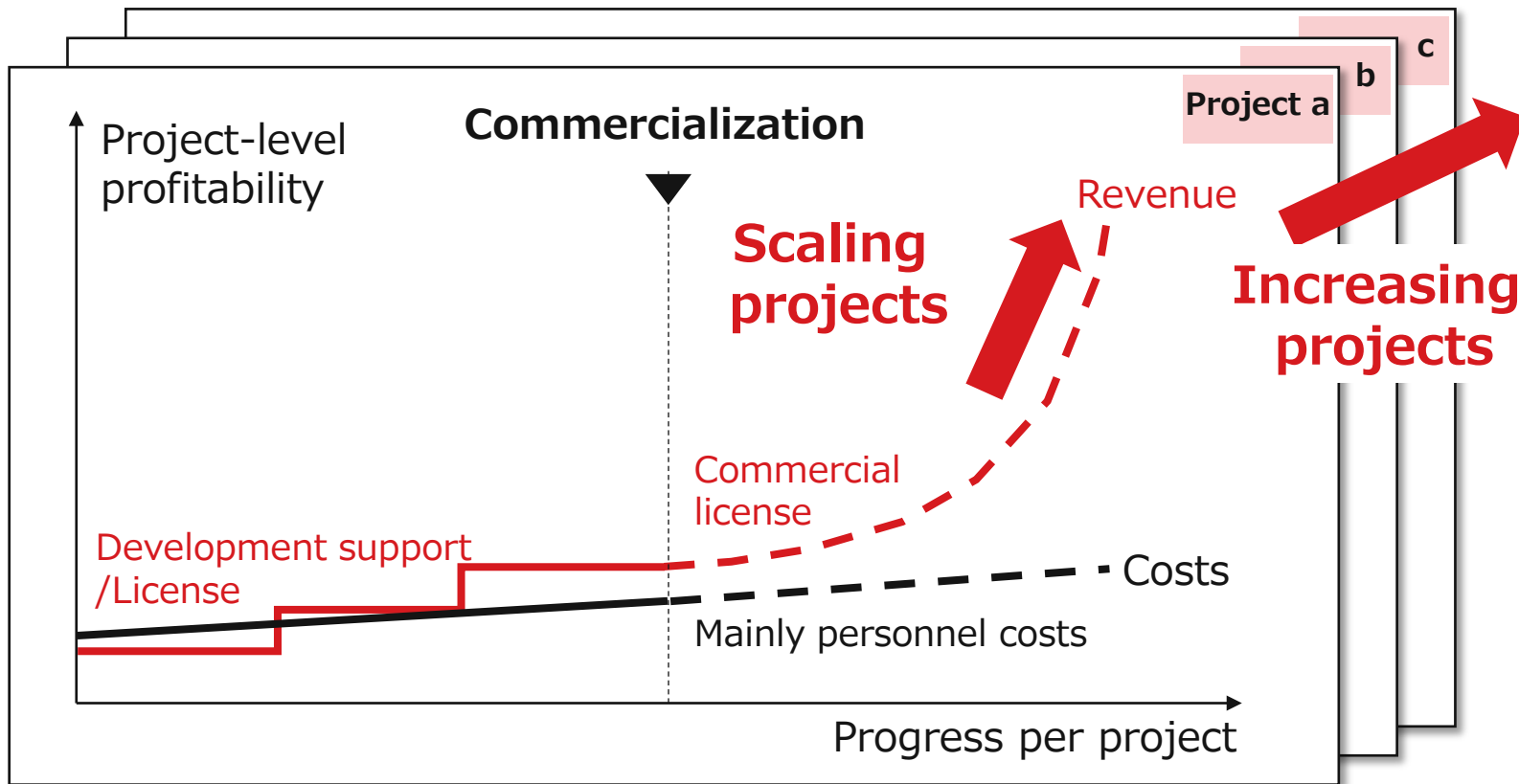
# Highlight for future growth strategy based on customers' commercialization



- With plans to have several customers launch their products using Kudan software from this fiscal year ending March 2023, **the transition from the "preparation phase" to the "harvest phase" is underway**
- To accelerate this transition, we will strengthen our business based on customers' commercialization
  - A Acceleration and expansion of customers' commercialization:** Strengthen support, technology development, and business development with the aim of increasing the number of projects to be commercialized and increasing profit at the project level
  - B Solution business launch:** Not only embedding Kudan technology in individual products, but also providing engineering service to accelerate new solution development that synchronize multiple products and expand their applications centered on Kudan technology (digital twin, robot platform, Metaverse, etc.)

# A Acceleration and expansion of customers' commercialization

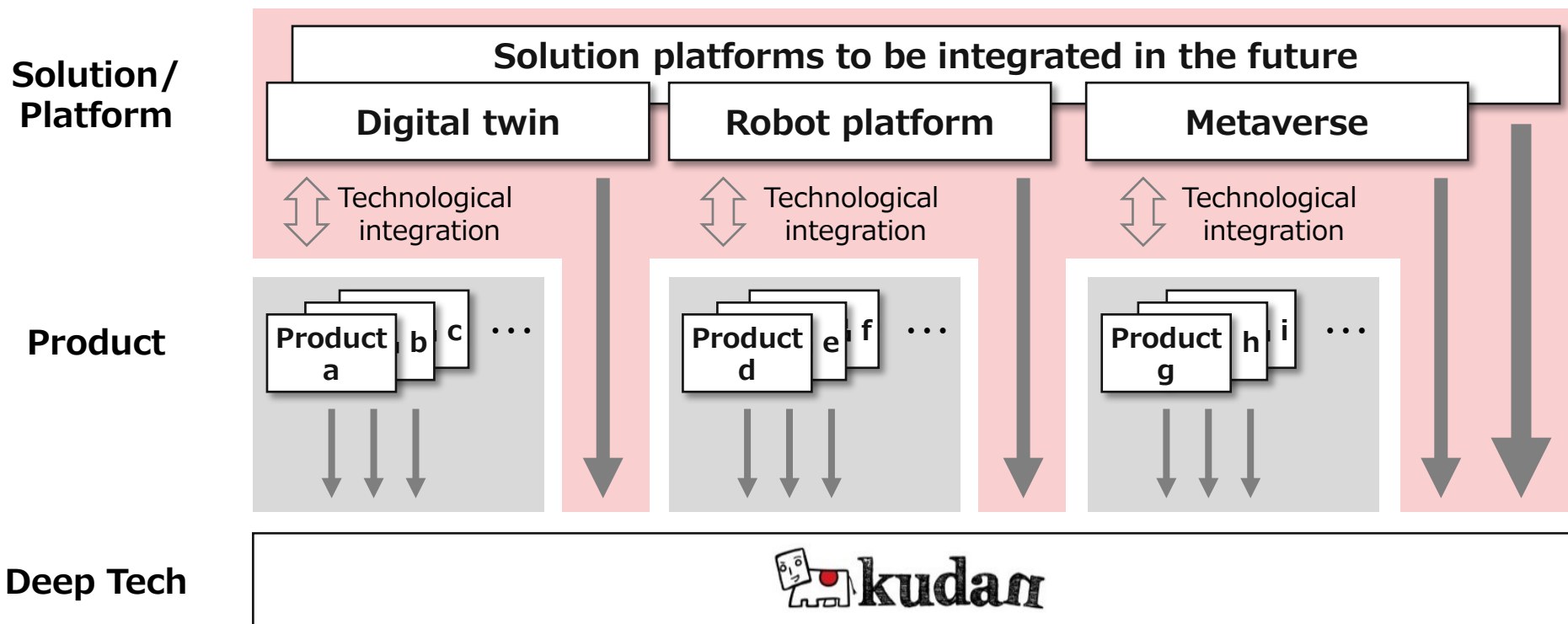
- **Scaling projects:** Strengthen support functions and technology development for the purpose of scaling projects in order to advance to the harvest phase at the project level, starting with the realization of customers' commercialization
- **Increasing the number of projects:** Strengthen business development, including global expansion, to increase the number of commercialization projects by leveraging the existing projects



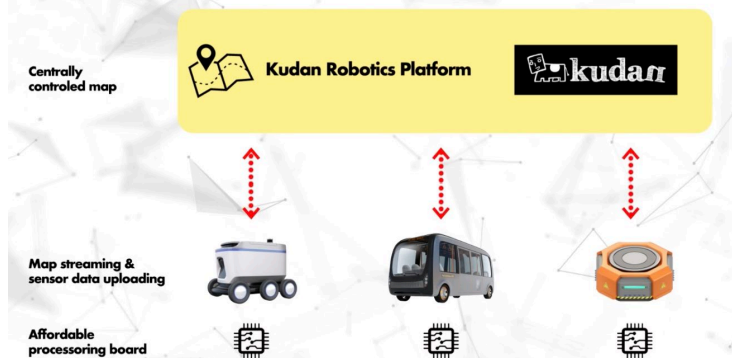
# B Solution Business Development

- Support the realization of solution platforms that allow multiple products to synchronize or expand their applications centered on Kudan technology
- Aim to improve profitability by taking customers' commercialization as a foothold for the solution business and by generating synergies from the solution business that will support the expansion of customers' commercialization

- Newly launched solutions business
- Existing product embedded business
- Revenue for development support and technology provision



## Solution examples



### ◆ Robotics platform

When a phase of introducing one robot on a trial basis is over and entering a phase of operating multiple types of robots on site, we are beginning to see the issue of disorganized maps and management tools for each type of robot

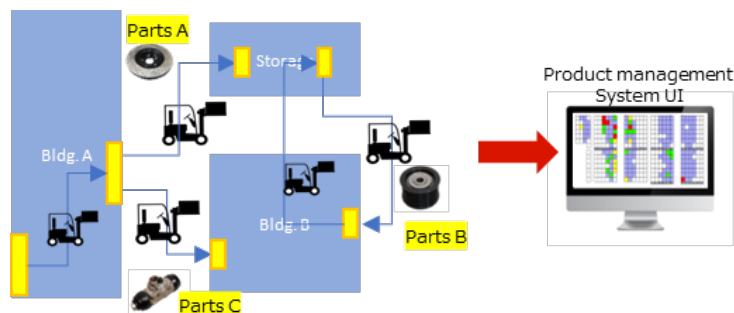
With Kudan's SLAM solution, we can develop **a unified platform that can centrally manage robots** from different companies



### ◆ Mapping solutions

3D maps are used for digital twin and simulation. On-site operations were sometimes difficult since the equipment for acquiring maps has been extremely expensive and it has been necessary to call in specialized companies to acquire and update maps.

Kudan's SLAM solution **enables inexpensive equipment to acquire highly accurate 3D maps.** Also, **the maps include feature points from which location information can be obtained** and can be developed into a number of robotic and Metaverse solutions.



### ◆ Location × AI DX Solutions

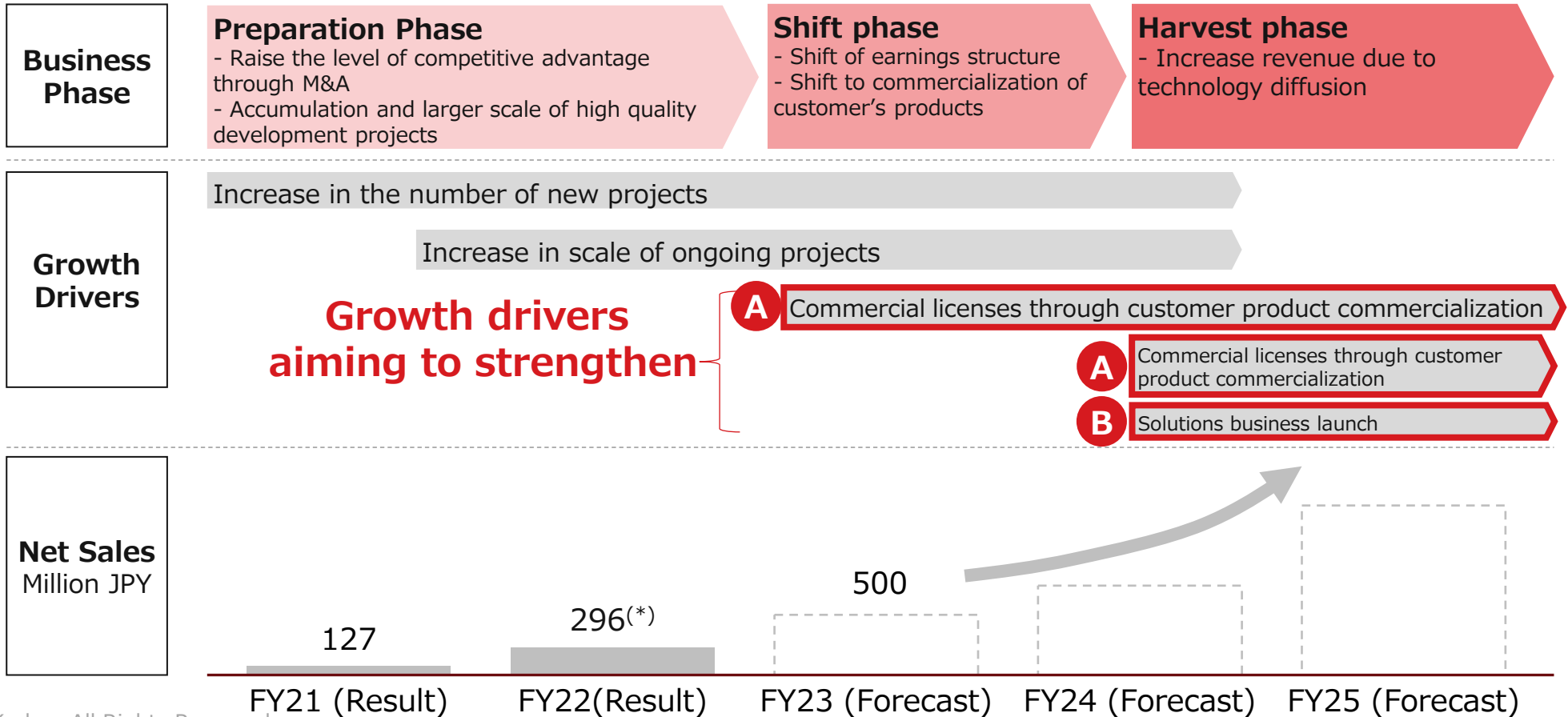
By combining location information from our SLAM with AI technology from partner companies, we can provide a completely new DX solution that has never been seen before.

For example, when parts are transported between buildings in a factory using forklifts in any direction, it has been difficult to manage in real time which parts and how many parts are in which storage area. To solve this problem, we will develop a DX solution that can manage parts in real time without using markers, RFID, etc. by **using AI to recognize what parts have been picked up and SLAM to recognize where they have been transported to.**

**SLAM with AI enable real-time, integrated management of complex parts inventory status across buildings**

# Shift to the harvest phase

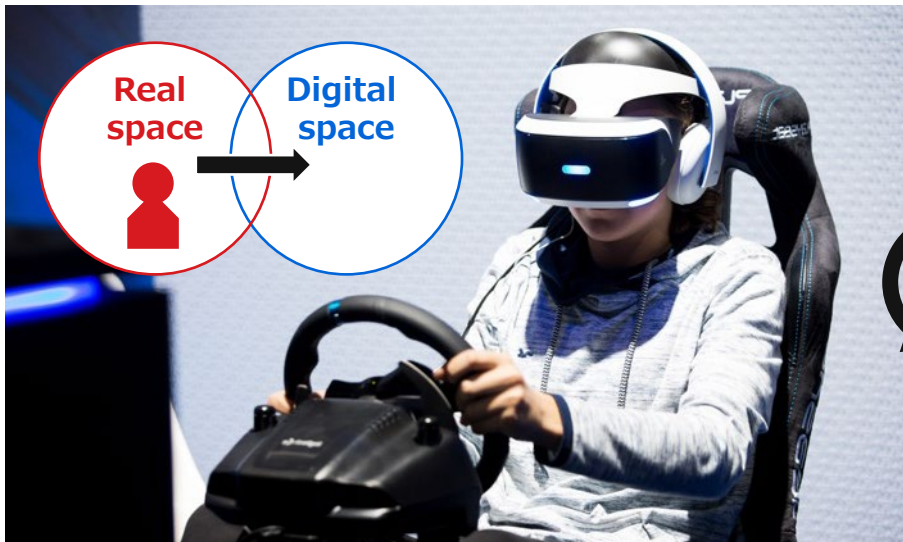
- Keep the strategy to shift earnings structure aiming for profitability and revenue model through the commercialization of customers' products to realize revenue growth from the fiscal year ending March 2024 onward
- Aim to shift to the harvest phase from "project-level profitability" to "business-level profitability" by strengthening growth drivers
- Depending on the commercialization of customers' products, Kudan aims to generate several million yen to several tens of millions of yen per project at the start of commercialization, and then to generate revenue in the hundreds of millions of yen per project as product sales expand



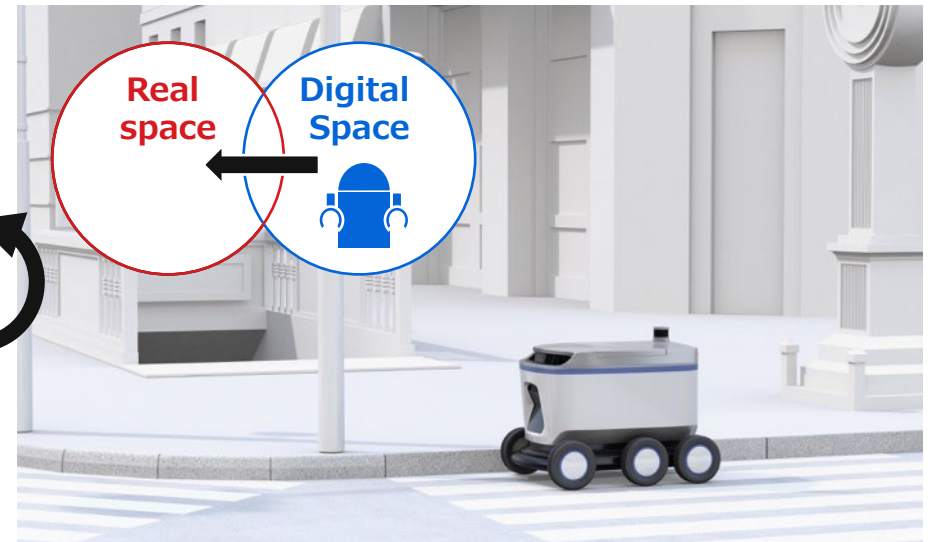
# Metaverse demand pushes us forward

- With the demand for Metaverse as a tailwind, Kudan's Artificial Perception/SLAM technology is the core technology of the Metaverse, which realizes the "coupling of real space and digital space," and further extends the Metaverse to integrate with robotics
- Capture the ongoing evolution of Metaverse demand for growth by providing versatile-purpose technology for both Metaverses

## Metaverse (AR/VR)



## Extended Metaverse (Robotics)



Metaverse evolves as real and digital spaces are more highly connected, such as robot operations via the Metaverse




# Mid- to long-term R&D investment for discontinuous growth

- In addition to developing its Deep Tech efforts, the company will invest in additional technological innovations for discontinuous growth over the mid to long term
- Due to the nature of an algorithm-layered Deep Tech company, the majority of R&D investment is in personnel costs, and the scale of additional investment in the future is expected to be about several additional engineers per year

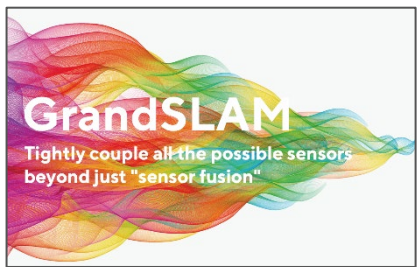
## Dramatic growth via mid-to-long term technological innovation

**Event-based camera SLAM**  
(Applied technology for next-generation cameras that imitate the visual nerve and retinal structure of living organisms. Further breakthrough technology for autonomous driving and robotics because it is ultra-high speed but stable even in dark place.)

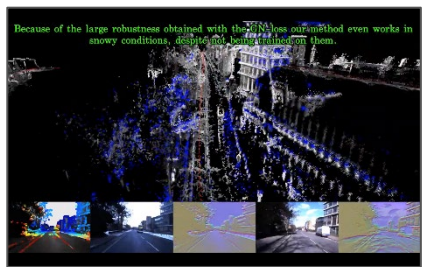


## Growth by capturing and strengthening the base upon areas where the demand is evident

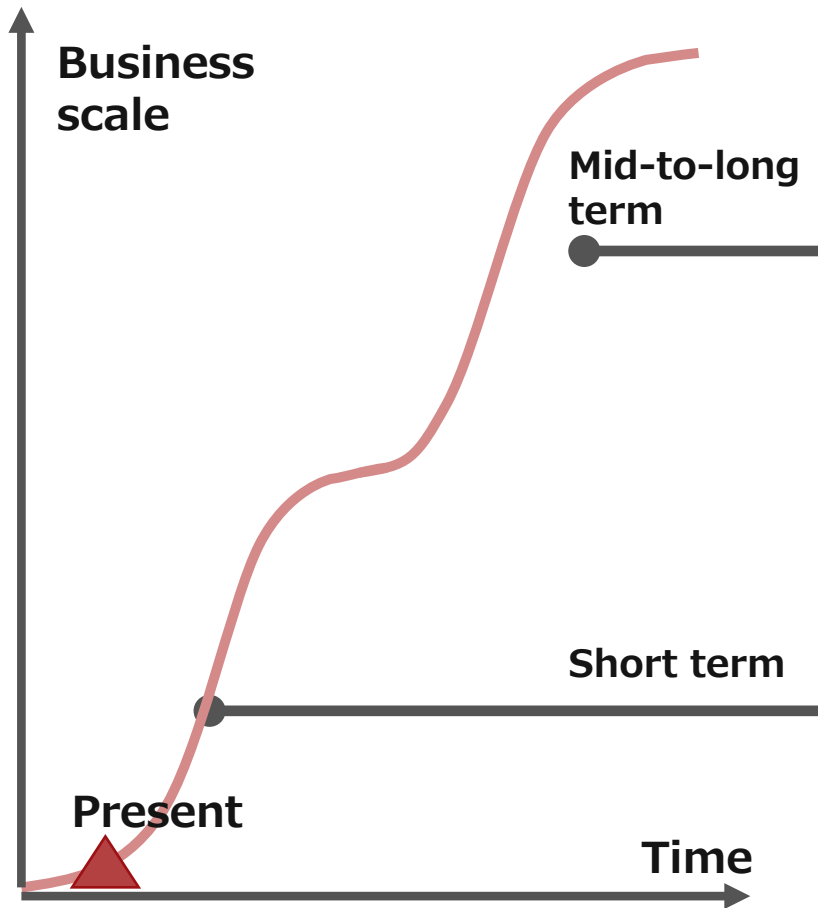
**GrandSLAM**  
(Tight coupling of major sensors)



**GN-Net/Super-point**  
(Combining SLAM with deep learning)



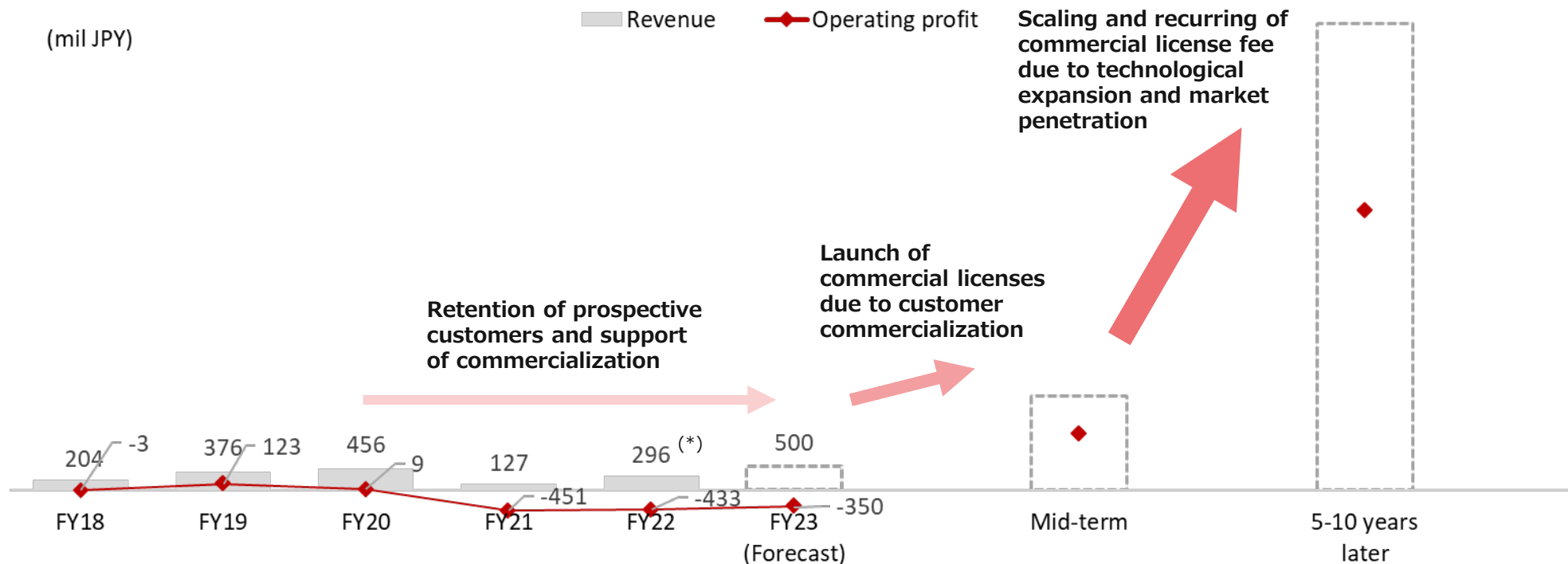
Because of the large robustness obtained with the GN-Net/Super-point method even works in snowy conditions, despite not being trained on them.



# Future growth potential (Mid- to Long-term)

- Stable commercialization from the cumulative customer projects creates technological penetration to the market, leading to recurring revenue from commercial licenses and significant growth in profit

Mid- to Long-term estimate



(\*) Revenue adjusted for the impact due to accounting standards change

- This document contains Kudan's plans, estimates and expectations for the future based on its current business situation and industry trends.
- All such projections for the future inherently involve uncertainty and a wide variety of risks.
- It is conceivable that risks both understood and unforeseen, uncertainties and other factors may cause actual results to differ from the projections contained within this document.
- Kudan offers no guarantee of the accuracy of its projections for the future and accepts that they may differ significantly from actual results.
- All projections for the future included in this document are based upon information available to Kudan as of August 15th, 2022, and may not be updated or changed to reflect future developments or changes in status.